











Variational physiologically informed solution to hemodynamic and perfusion response estimation from ASL fMRI data

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Abstract

Functional Arterial Spin Labeling (fASL) [1] MRI can provide a quantitative measurement of cerebral blood flow and its variations elicited by specific tasks. The statistical analysis of fASL has been done using

- General linear model (GLM) [2] with regressors based on the canonical hemodynamic response function.
- Joint detection-estimation (JDE) [3] framework which allows the extraction of both task-related perfusion and hemodynamic responses not restricted to canonical shapes. Previous ASL-JDE attempts have been based on Markov Chain Monte Carlo (MCMC) methods, very computationally expensive. Contribution: a variational expectation-maximization (VEM) algorithm [4] for hemodynamic and perfusion responses estimation.

Framework

ASL fMRI [1] data provide a quantitative measurement of blood perfusion changes elicited by task performance Magnetically tagged image (Tag)



Time delay (1) to (2): Labeled water reaches capillary bed and is exchanged with water

molecules in the tissue

signal change



or stimulus delivery in the brain

control tag control . . .



Tag inflowing arterial blood by magnetic inversion

Control image

Repeat acquisition without labeling inflowing blood

Ref: http://fmri.research.umich.edu/research/main topics/asl.php

The difference in magnetization is proportional to regional cerebral blood flow

ASL Joint detection estimation (JDE) framework [3]



Physiologically informed JDE [5]

We consider physiological information in the estimation as a prior knowledge of the response functions $\, \, {f g} = \Omega {f h} \,$ models coupling Stimulation CBF-HRF hemodynamic perfusion response response function function →BOLD Balloon hemodynamic models

terms. We estimate the parameters of this model.

HRLs) labels (active/non-active)



Expectation-Maximization

E-step: $\tilde{p}^{(r)} = \arg \max F(\tilde{p}, \boldsymbol{\theta}^{(r)})$ **M-step:** $\boldsymbol{\theta}^{(r+1)} = \arg \max F(\tilde{p}^{(r)}, \boldsymbol{\theta})$

Maximizing function *F* is equivalent to minimizing the Kullback-Leibler divergence between \tilde{p} and the true posterior $p(\boldsymbol{a}, \boldsymbol{h}, \boldsymbol{c}, \boldsymbol{g}, \boldsymbol{q} | \boldsymbol{y})$

Variational EM

Restrict solutions to the ones that allow $\tilde{p}(\boldsymbol{a}, \boldsymbol{h}, \boldsymbol{c}, \boldsymbol{g}, \boldsymbol{q}) = \tilde{p}_a(\boldsymbol{a}) \ \tilde{p}_h(\boldsymbol{h}) \ \tilde{p}_c(\boldsymbol{c}) \ \tilde{p}_g(\boldsymbol{g}) \ \tilde{p}_q(\boldsymbol{q})$

E and M step can be decomposed in stages corresponding to the different parameters The E-H step, for example, goes:

 $\tilde{p}_h = \arg \max F(\tilde{p}_a \ \tilde{p}_h \ \tilde{p}_c \ \tilde{p}_g \ \tilde{p}_q; \theta)$ $\tilde{p}_h \in \mathcal{D}_H$

Variational Expectation-Maximization

We can constraint the search to pointwise estimates h and \tilde{g} by replacing the probabilities on h and gby Dirac functions: $\tilde{p} = \tilde{p}_a \ \delta_{\tilde{h}} \ \tilde{p}_c \ \delta_{\tilde{g}} \ \tilde{p}_q$

And so: $h = \arg\max F(\tilde{p}_a \delta_{\tilde{h}} \tilde{p}_c \delta_{\tilde{g}} \tilde{p}_q; \theta)$ We can easily include constraints like $\|h\|_2^2 = 1$, $\|g\|_2^2 = 1$

Results



Comparison with stochastic ASL-JDE

References

Both methods have a similar performance, but VEM recovers better response levels while MCMC recovers better response functions



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