

Features Selection in Spatial Point Processes

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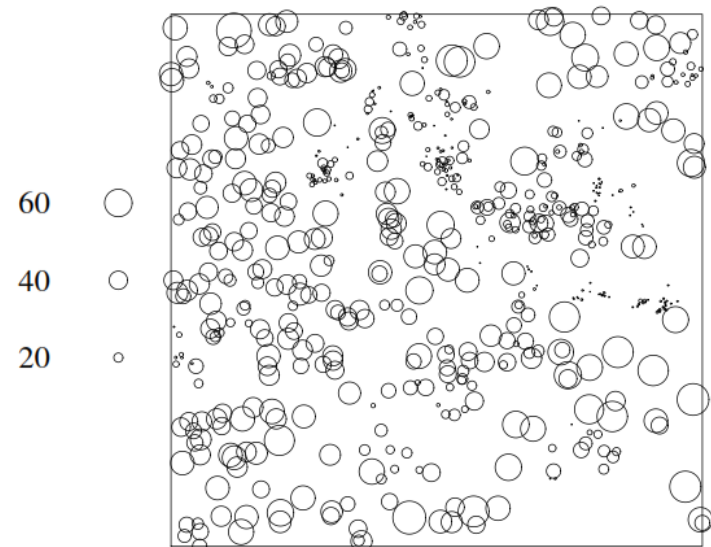
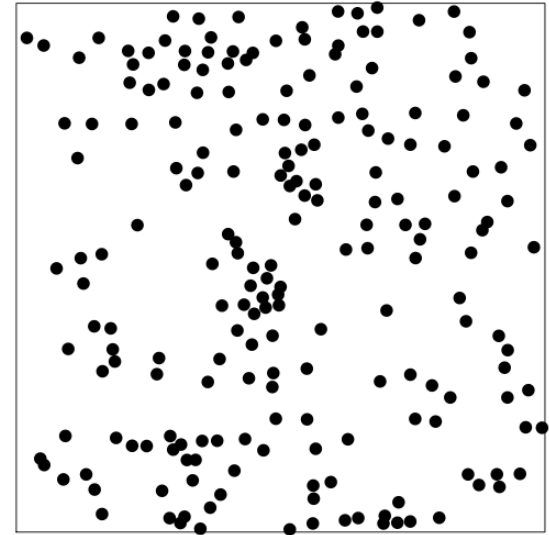
- **Spatial Point Processes**
 - Few Examples
 - Introduction to Spatial Point Processes
 - Basic Point Processes
- **Features Selection**
 - Why should be?
 - What we propose
- **Further Research**
 - Selection of Covariates Techniques
 - More Point Processes Models
 - Estimation of Intensity Function

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Few Examples

- 204 seedlings and saplings of Japanese Black Pine
- 10 x 10 meters sampling region
- Objective : to understand ecological processes (competition for resources and spatial variation in the landscape)

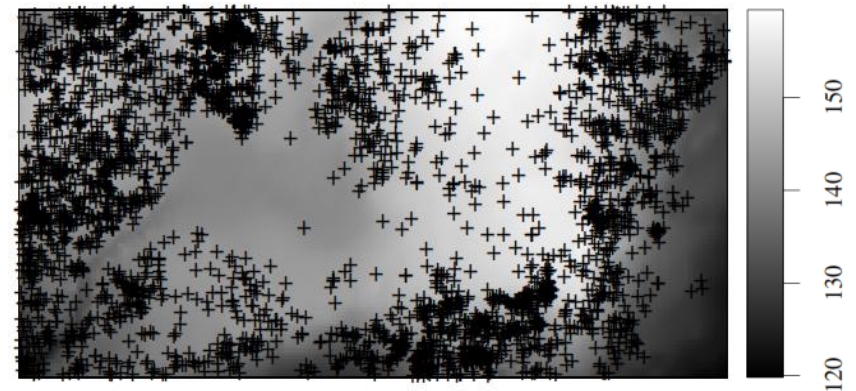
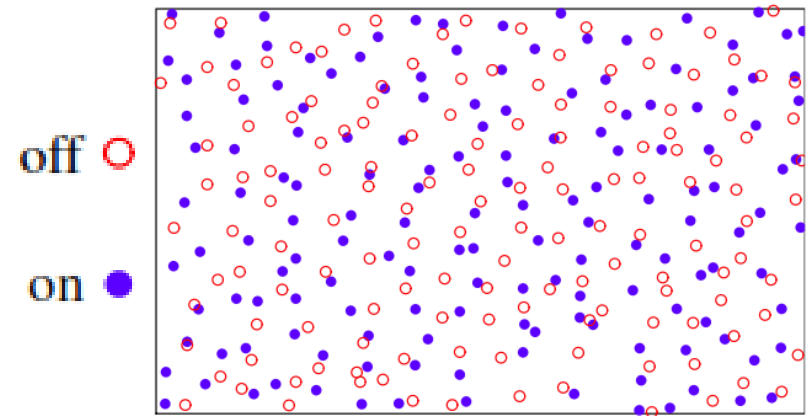
- Forest survey, size of each tree was measured by its diameter at breast height (dbh)
- 584 Longleaf Pine (*Pinus palustris*)
- 200 × 200 meters region in southern Georgia (USA)



Few Examples

- Amacrine cells in the retina of a rabbit
- cells categorised as either “on” or “off” according to their response to stimuli

- 3605 trees in a tropical rainforest, with a supplementary grid map of the terrain elevation (altitude)
- The covariate $Z(u)$ is the altitude at location u
- Research questions for investigation include whether the forest density depends on the terrain



Introduction to Spatial Point Processes

- **Point Processes on \mathbf{R}^d**

- A spatial point processes X is a random countable subset of a space S
- N_{if} : space of locally finite configurations, i.e.,
$$N_{if} = \{X \subseteq S : n(X_B) < \infty \text{ for all bounded } B \subseteq S\}$$
- x, y, \dots denote points in B while ξ, φ, \dots denote points in S

- **Intensity ($\rho(u)$)**

- Dividing the total number of points by the area
- Basic descriptive characteristic of a point process (First Moment)

- **Marked Point Processes**

- Let Y be a point process on $T \subseteq \mathbf{R}^d$, given some space M , if a random mark process $m_\xi \in M$ is attached to each point $\xi \in Y$, then

$$X = \{(\xi, m_\xi) : \xi \in Y\}$$

is called a marked point process with points in T and mark space M

Basic Point Processes

- **Poisson Point Process**

- $n(X_B)$ is a Poisson random variable
- If B_1, B_2, \dots are disjoint regions of space then $n(X_{B_1}), n(X_{B_2}), \dots$ are independent random variables
- Given that $n(X_B) = n$, the n points are independent and uniformly distributed in B
- Described by its intensity function $\rho(u)$
- Likelihood for θ

$$\mathcal{L}(\theta; x) = \prod_{u \in X_W} \rho(u; \theta) \exp \left(\int_W (1 - \rho(u; \theta)) du \right)$$

$$\text{Log } \mathcal{L}(\theta; x) = \sum_{u \in X_W} \log \rho(u; \theta) + \left(\int_W (1 - \rho(u; \theta)) du \right)$$

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Why should be?

- **Real Case**

- Study of 1251 trees in tropical forest of Barro Colorado Island (Panama)
- 15 covariates include 13 types of soil-borne resources, terrain elevation, and slope

- **Multicollinearity**

- Can make us select wrong model
- Choose wrong variables, or even, spurious variables
- Give rise to issue of over fitting
- Under fit which leads to bias

- **Need Selection of Covariates**

- Mitigate over fitting which results in variance inflation
- Mitigate under fitting which leads to bias
- Find 'true' covariates and make it more interpretable

What we propose

- **Poisson Point Process**

- Log likelihood for θ

$$\begin{aligned} \text{Log } \mathcal{L}(\theta; x) &= \sum_{u \in X_w} \log \rho(u; \theta) + \left(\int_w (1 - \rho(u; \theta)) du \right) \\ &= \sum_{u \in X_w} \log \rho(u; \theta) - \left(\int_w \rho(u; \theta) du \right) \end{aligned}$$

- **Coarse quadratum approximation**

$$\int_w \rho(u; \theta) \approx \sum_{j=1}^{n+m} \rho(u_j; \theta) w_j$$

What we propose

$$\text{Log } \mathcal{L}(\theta; x) \approx \sum_{i=1}^n \log \rho(u_j; \theta) - \sum_{j=1}^{n+m} \rho(u_j; \theta) w_j$$

$$\text{Log } \mathcal{L}(\theta; x) \approx \sum_{j=1}^{n+m} (I_j \log \rho(u_j; \theta) - \rho(u_j; \theta) w_j)$$

$$\text{Log } \mathcal{L}(\theta; x) \approx \sum_{j=1}^{n+m} (y_j \log \rho(u_j; \theta) - \rho(u_j; \theta)) w_j \quad \text{for } y_j = I_j / w_j$$

Equivalent to fitting a weighted Poisson generalized linear model

What we propose

- **Penalized Maximum Likelihood**

$$-\mathcal{L}(\theta; x) + np_\gamma(\theta)$$

Minimizing that penalized likelihood :

Simultaneously select variables and estimate the parameter

- Ridge (L2)

$$p_\gamma(\theta) = \gamma \sum_{j=1}^p \theta_j^2$$

- LASSO (L1)

$$p_\gamma(\theta) = \gamma \sum_{j=1}^p |\theta_j|$$

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Further Research

- **Selection of Covariates Techniques**
 - Least Absolute Shrinkage and Selection Operator (LASSO)
 - Adaptive LASSO
 - Elastic net
 - Dantzig Selector
 - Smoothly Clipped Absolute Deviation (SCAD)
- **More Point Processes Models**
 - Cox Point Process
 - Gibbs Point Process
- **Estimation of Intensity Function**
 - Parametric
 - Nonparametric

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Thank you for your attention!!