











Variational physiologically informed solution to hemodynamic and perfusion response estimation from ASL fMRI data

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Abstract

Functional Arterial Spin Labeling (fASL) [1] MRI can provide a quantitative measurement of cerebral blood flow and its variations elicited by specific tasks. The statistical analysis of fASL has been done using

- General linear model (GLM) [2] with regressors based on the canonical hemodynamic response function.
- Joint detection-estimation (JDE) [3] framework which allows the extraction of both task-related perfusion and hemodynamic responses not restricted to canonical shapes. Previous ASL-JDE attempts have been based on Markov Chain Monte Carlo (MCMC) methods, very computationally expensive.
 Contribution: a variational expectation-maximization (VEM) algorithm [4] for hemodynamic and perfusion responses estimation.

Framework

ASL fMRI [1] data provide a quantitative measurement of blood perfusion changes elicited by task performance

Magnetically tagged image (Tag)



Time delay (1) to (2): Labeled water reaches capillary bed and is exchanged with water molecules in the tissue



or stimulus delivery in the brain

control tag control



Tag inflowing arterial blood by magnetic inversion

Control image

labeling inflowing blood

Repeat acquisition without

1.



signal change

The difference in magnetization is proportional to regional cerebral blood flow

Ref: http://fmri.research.umich.edu/research/main_topics/asl.php

ASL Joint detection estimation (JDE) framework [3]



Physiologically informed JDE [5]

We consider physiological information in the estimation as a prior knowledge of the response functions $\mathbf{g} = \Omega \mathbf{h}$ Stimulation \mathbf{f} models coupling CBF-HRF perfusion response function \mathbf{g} models coupling CBF-HRF perfusion response function \mathbf{g} models coupling CBF-HRF

terms. We estimate the parameters of this model.

) (HRLs) q labels (active/non-active)



Expectation-Maximization

E-step: $\tilde{p}^{(r)} = \underset{\tilde{p}}{\operatorname{arg max}} F(\tilde{p}, \boldsymbol{\theta}^{(r)})$ **M-step:** $\boldsymbol{\theta}^{(r+1)} = \underset{\boldsymbol{\theta}}{\operatorname{arg max}} F(\tilde{p}^{(r)}, \boldsymbol{\theta})$

Maximizing function *F* is equivalent to minimizing the Kullback-Leibler divergence between \tilde{p} and the true posterior p(a, h, c, g, q | y)

Variational EM

Restrict solutions to the ones that allow $\tilde{p}(\boldsymbol{a}, \boldsymbol{h}, \boldsymbol{c}, \boldsymbol{g}, \boldsymbol{q}) = \tilde{p}_a(\boldsymbol{a}) \tilde{p}_h(\boldsymbol{h}) \tilde{p}_c(\boldsymbol{c}) \tilde{p}_g(\boldsymbol{g}) \tilde{p}_q(\boldsymbol{q})$

E and M step can be decomposed in stages corresponding to the different parameters The E-H step, for example, goes: $\tilde{n}_{L} = \arg \max F(\tilde{n}_{L} | \tilde{n}_{L} | \tilde{n}_{L}$

 $\tilde{p}_h = \operatorname*{arg\,max}_{\tilde{p}_h \in \mathcal{D}_H} F(\tilde{p}_a \ \tilde{p}_h \ \tilde{p}_c \ \tilde{p}_g \ \tilde{p}_q; \theta)$

Variational Expectation-Maximization

We can constraint the search to pointwise estimates \tilde{h} and \tilde{g} by replacing the probabilities on h and g by Dirac functions: $\tilde{p} = \tilde{p}_a \ \delta_{\tilde{h}} \ \tilde{p}_c \ \delta_{\tilde{g}} \ \tilde{p}_q$

And so: $\tilde{h} = \arg \max_{\tilde{h}} F(\tilde{p}_a \delta_{\tilde{h}} \tilde{p}_c \delta_{\tilde{g}} \tilde{p}_q; \theta)$ We can easily include constraints like $\|h\|_2^2 = 1$, $\|g\|_2^2 = 1$

Results



Comparison with stochastic ASL-JDE

References

Both methods have a similar performance, but VEM recovers better response levels while MCMC recovers better response functions



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