

Variational solution to hemodynamic and perfusion response estimation from ASL fMRI data

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BOLD: Qualitative functional MRI

Blood Oxygen Level Dependent [Ogawa et al, PNAS 1990]

What does BOLD contrast really measure?

BOLD measures the ratio of oxy- to deoxy-hemoglobin in the blood



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De-oxyhemoglobin (Hb): Oxyhemoglobin (HbO2):

paramagnetic



Signal decrease





Signal increase



ASL: Quantitatively imaging cerebral perfusion

Arterial Spin Labeling [Williams et al, PNAS 1992]

WHAT?

 Cerebral perfusion: Delivery of nutritive blood to the brain tissue capillary bed

WHY?

 Quantification is important: eg. perfusion altered in various diseases (stroke, tumors)

ASL ✓ direct quantitative measure ✓ cerebral blood flow ¥ low SNR

BOLD



Arterial Spin Labeling data acquisition

Tag image

Tag inflowing arterial blood by magnetic inversion



Control Image (4) - Tag Image (2)



Control image

Repeat experiment without labeling inflowing blood



Statistical analysis of ASL fMRI data

CBF

ASL data contain both hemodynamic & perfusion components



CBF + blood volume + oxygen consumption

Statistical analysis of ASL fMRI data

► GLM

Unique fixed canonical hemodynamic response function (HRF) [Hernandez-Garcia et al, 10, Mumford et al, 06]

Inaccurate PRF shapes

Joint Detection-Estimation (JDE)

Separate estimation of 2 response functions (HRF & PRF) Use of MCMC methods [Vincent et al, 13, Frau-Pascual et al, 14]

Computationally very expensive







Providing an efficient solution to hemodynamic and perfusion response estimation from ASL fMRI data

Based on:

- Variational Expectation-Maximization [Chaari et al, 12]
 - Acceptable computational times
- Physiological prior information

ASL signal model



Physiological prior



Variational Expectation Maximization

Expectation Maximization.

E-step:
$$\tilde{p}^{(r)} = \underset{\tilde{p}}{\arg \max} F(\tilde{p}, \theta^{(r)})$$

M-step: $\theta^{(r+1)} = \underset{\theta}{\arg \max} F(\tilde{p}^{(r)}, \theta)$

being

$$F(\tilde{p}, \theta) = \mathrm{E}_{\tilde{p}} \left[\log p(y, a, h, c, g, q ; \theta) \right] \underbrace{-\mathrm{E}_{\tilde{p}} \left[\log \tilde{p}(a, h, c, g, q) \right]}_{\text{entropy of } \tilde{p}}$$

 Variational EM: class of probability distributions restricted to the set of distributions that satisfy

$$ilde{
ho}(a,h,c,g,q) = ilde{
ho}_{a}(a) \; ilde{
ho}_{h}(h) \; ilde{
ho}_{c}(c) \; ilde{
ho}_{g}(g) \; ilde{
ho}_{q}(q)$$

VEM steps (1)

The E-step becomes an approximate E-step that can be further decomposed into five stages updating the different variables:

The M-step can also be divided into separate steps:



VEM steps (2)

The E-step become: **E-H-step:** $\tilde{p}_h = \underset{\tilde{p}_h \in \mathcal{D}_H}{\arg \max} F(\tilde{p}_a \ \tilde{p}_h \ \tilde{p}_c \ \tilde{p}_g \ \tilde{p}_q; \theta)$ **E-G-step:** $\tilde{p}_g = \underset{\tilde{p}_g \in \mathcal{D}_G}{\arg \max} F(\tilde{p}_a \ \tilde{p}_h \ \tilde{p}_c \ \tilde{p}_g \ \tilde{p}_q; \theta)$

and similar for the rest of the variables. The M-step can also be divided into separate steps:

$$\begin{split} \theta &= \operatorname*{arg\,max}_{\theta \in \Theta} \left[\mathrm{E}_{\tilde{p}_{a}\tilde{p}_{c}} \big[\log p(\boldsymbol{y} \mid \boldsymbol{a}, \tilde{\boldsymbol{h}}, \boldsymbol{c}, \tilde{\boldsymbol{g}}; \boldsymbol{\alpha}, \ell, \sigma^{2}) \big] \\ &+ \mathrm{E}_{\tilde{p}_{a}\tilde{p}_{q}} \big[\log p(\boldsymbol{a} \mid \boldsymbol{q}; \boldsymbol{\mu}_{a}, \sigma_{a}) \big] + \log p(\tilde{\boldsymbol{h}}; \boldsymbol{v}_{h}) \\ &+ \mathrm{E}_{\tilde{p}_{c}\tilde{p}_{q}} \big[\log p(\boldsymbol{c} \mid \boldsymbol{q}; \boldsymbol{\mu}_{c}, \sigma_{c}) \big] + \log p(\tilde{\boldsymbol{g}}; \boldsymbol{v}_{g}) \\ &+ \mathrm{E}_{\tilde{p}_{q}} \big[\log p(\boldsymbol{q}; \boldsymbol{\beta}) \big] \bigg] \end{split}$$

Constraints on h and g

We can constraint the search to pointwise estimates \tilde{h} and \tilde{g} by replacing the probabilities on h and g by Dirac functions:

$$\tilde{p} = \tilde{p}_a \, \delta_{\tilde{h}} \; \tilde{p}_c \; \delta_{\tilde{g}} \; \tilde{p}_q$$

so that, for example for H, the E-H step

$$\begin{split} \tilde{p}_{h} &= \mathop{\arg\max}_{\tilde{p}_{h} \in \mathcal{D}_{H}} F(\tilde{p}_{a} \, \tilde{p}_{h} \, \tilde{p}_{c} \, \tilde{p}_{g} \, \tilde{p}_{q}; \theta) \\ \text{becomes} \quad \tilde{h} &= \mathop{\arg\max}_{\tilde{h}} F(\tilde{p}_{a} \delta_{\tilde{h}} \tilde{p}_{c} \delta_{\tilde{g}} \tilde{p}_{q}; \theta) \end{split}$$

This facilitates the inclusion of constraints on *h* and *g* like $||h||_2^2 = 1$ and $||g||_2^2 = 1$.

Simulation results

Artificial data generation

- Repetition time: TR = 3 s
- Number of scans: N = 288
- White noise $b_j \sim \mathcal{N}(0, 2)$
- Response functions simulated with physiological model [Friston et al, 00]



- Fast event-related paradigm: mean ISI= 5 s.
- 1 experimental condition 20 × 20 binary activation label maps:

hemodyn. maps $\sim \mathcal{N}(2.2, 0.3)$



perfusion maps $\sim \mathcal{N}(1.6, 0.3)$



Simulation results: Low SNR scenario, TR = 3s



• Response levels



Simulation results: Low SNR scenario, TR = 3s

Comparison to MCMC solution of joint detection estimation (JDE):



Real data

Paradigm: fast event-related design (mean ISI = 5.1s.), with 60 auditory and visual stimuli



Conclusions

- Jointly detecting activity and estimating hemodynamic and perfusion responses from functional ASL data
- It facilitates the inclusion of additional information

Future directions

- Performance optimization
- Investigation of other constraints

Thanks for your attention