

Mixture of Heavy-Tailed distributions for Bivariate Precipitation Data

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Var Flood June 15th 2010



- warm sea
- mountainous landscape
- warm air from Africa

400 mm of rain in 24h \approx 5 months of precipitation

no similar event since 1827

Background

Machine learning



Yoshua Bengio

Extreme-Value Theory



Vilfredo Pareto 1848-1923

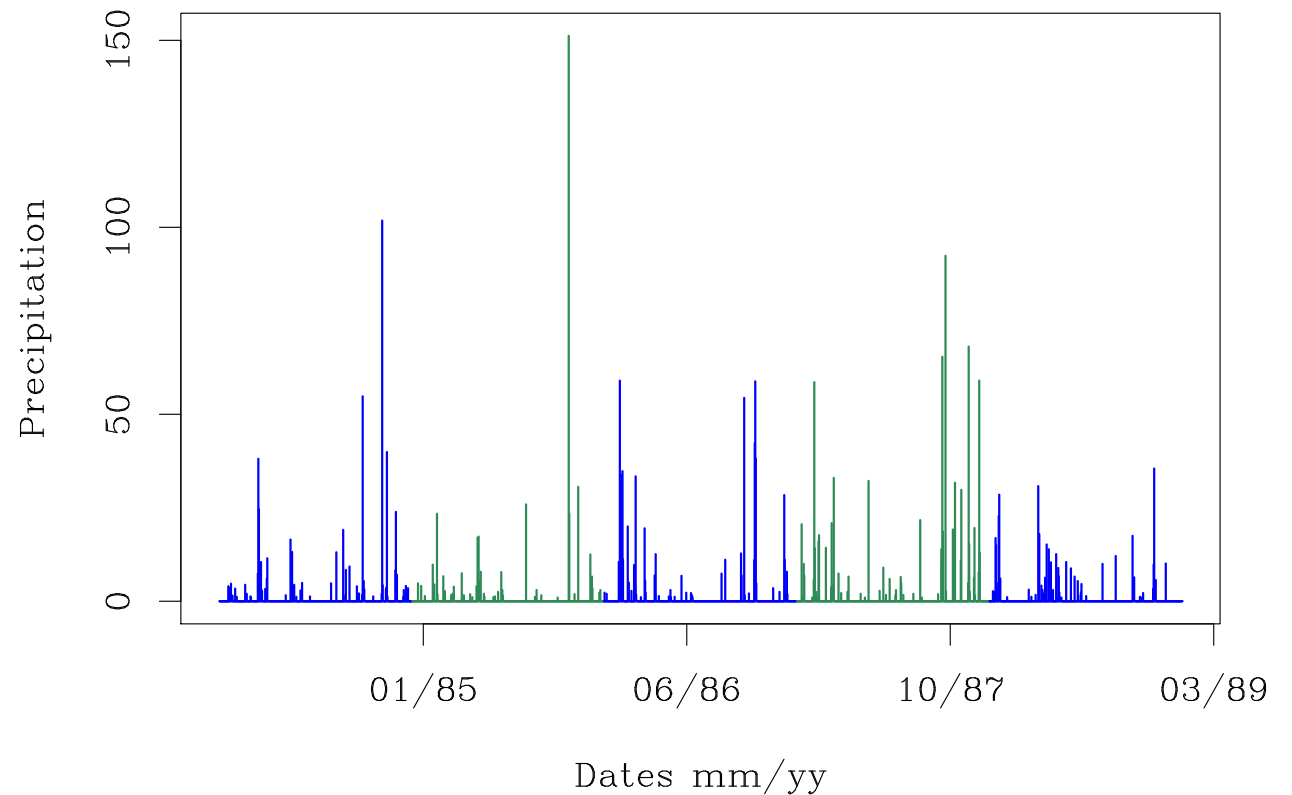
Bridge the gap between non-parametric and extreme-value models

Outline

1. Precipitation data
2. Outline of the bivariate density model:
mixture of bivariate distributions with a heavy tail along 1D projections
3. Hybrid Pareto Distribution
4. Bivariate Hybrid Pareto Distribution
5. Mixture learning and initialization
6. Synthetic examples and precipitation data
7. Future work

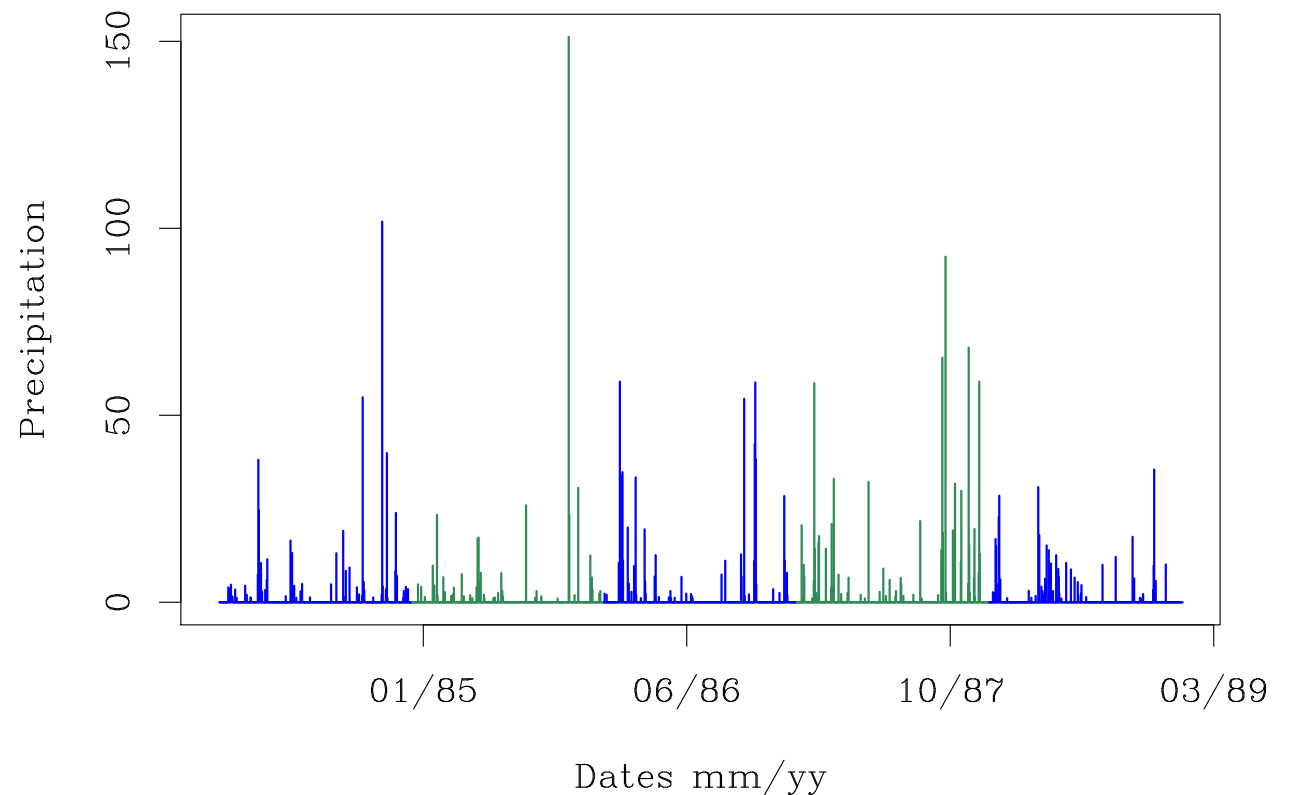
Precipitation Data

- Intermittency
- Temporal and spatial dependence
- Inter-annual / intra-annual variability
- extreme values



Precipitation Data

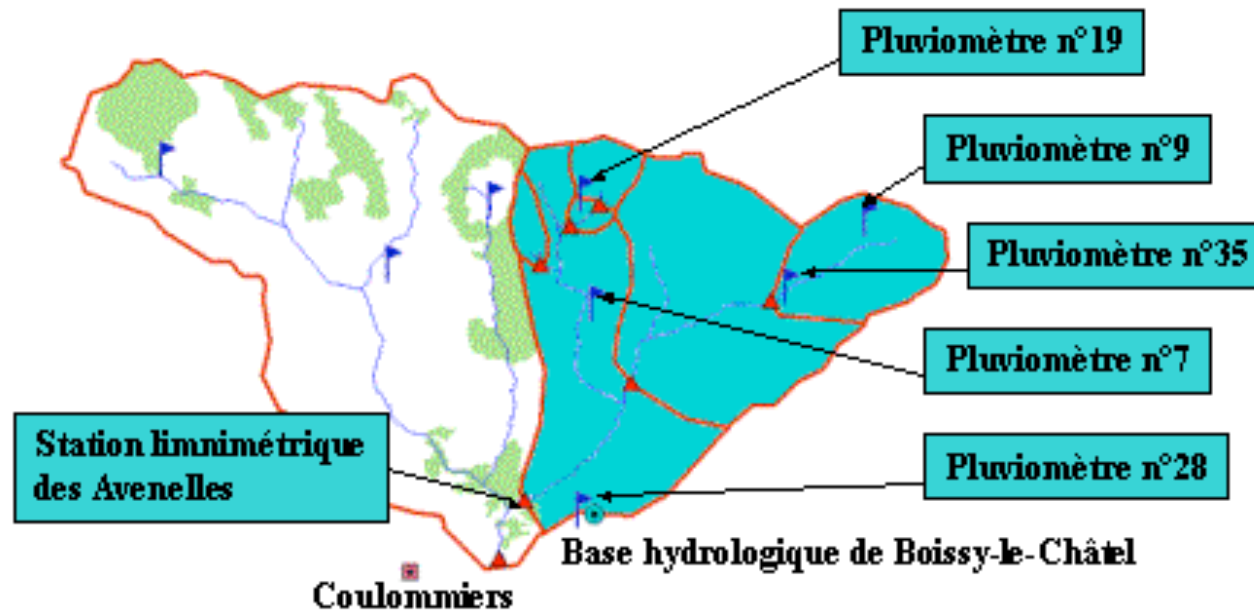
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- Inter-annual / intra-annual variability
- **extreme values**



Motivation

- Simulate runoff from hydrological models:
spatial rain field over the basin
- Evaluate the impact of climate change :
model precipitation given large scale atmospheric variables given by GCMs
- Dimension of dams and agricultural practice

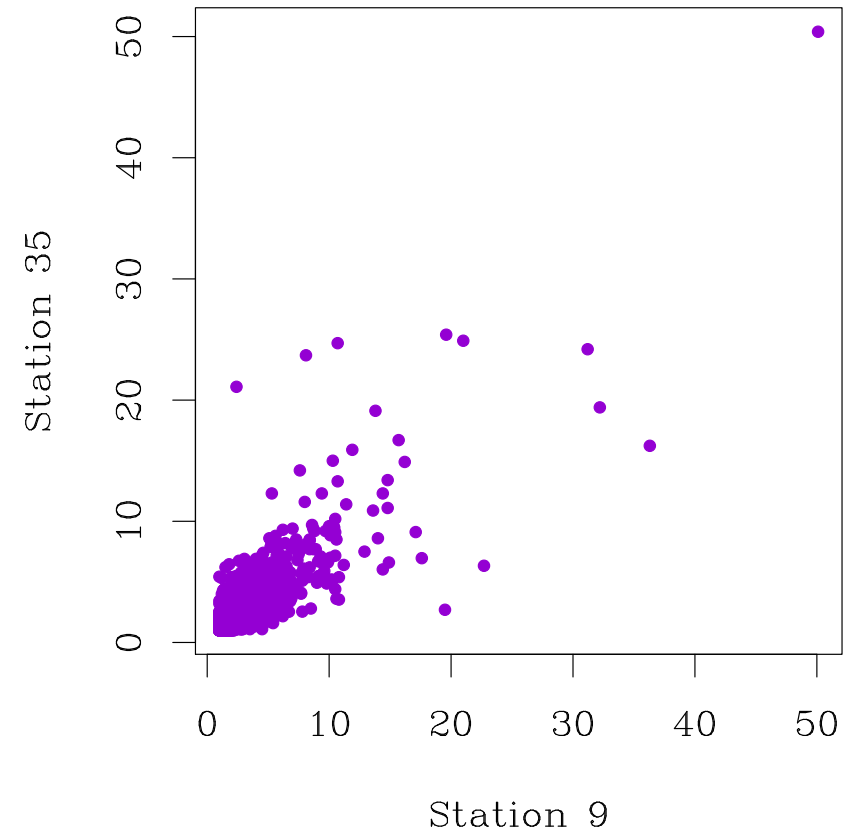
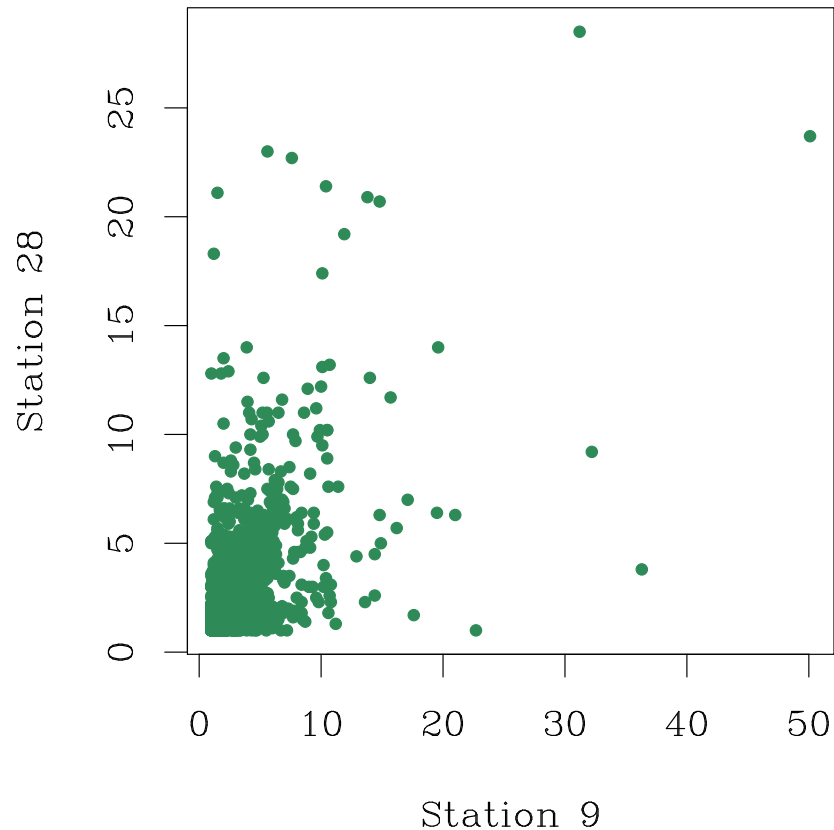
Avenelles Basin



★ **Positive hourly precipitation** (> 1 mm) for three stations of the Orgeval Basin, near Paris

★ **Data span 1972 to 2002** for about **3000** positive observations

Precipitation



★ **Spatially apart/close stations** show a more wide spread/narrow pattern

★ Dependence in the **central part** might differ from dependence in the **extremes**

Bivariate Mixture Model

Two key aspects of the precipitation data

★ Model the dependence structure of the extreme observations

Usually described either by the **spectral measure** or the **copula function**

Bivariate Mixture Model

Two key aspects of the precipitation data

- ★ **Model the dependence structure of the extreme observations**

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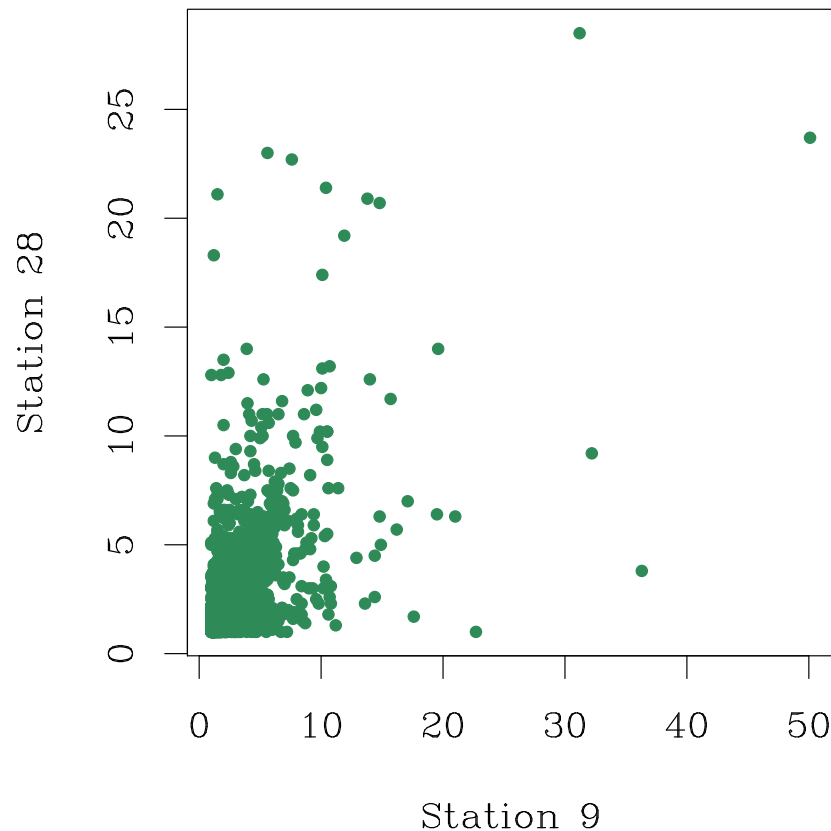
- ★ **Full density estimation: central and extremal areas**

Perform estimation of the **margins** and of the **dependence structure** at once

Extremal Dependence Structure

- ★ **Pseudo-polar coordinates:** angle ω and radius r
- ★ **Decomposition of the density for large values:**
product of the **angular spread** times the **radial distance**
- ★ **Angular spread** can be described by the **spectral measure**
- ★ **Radial distance** depends on the **margins**

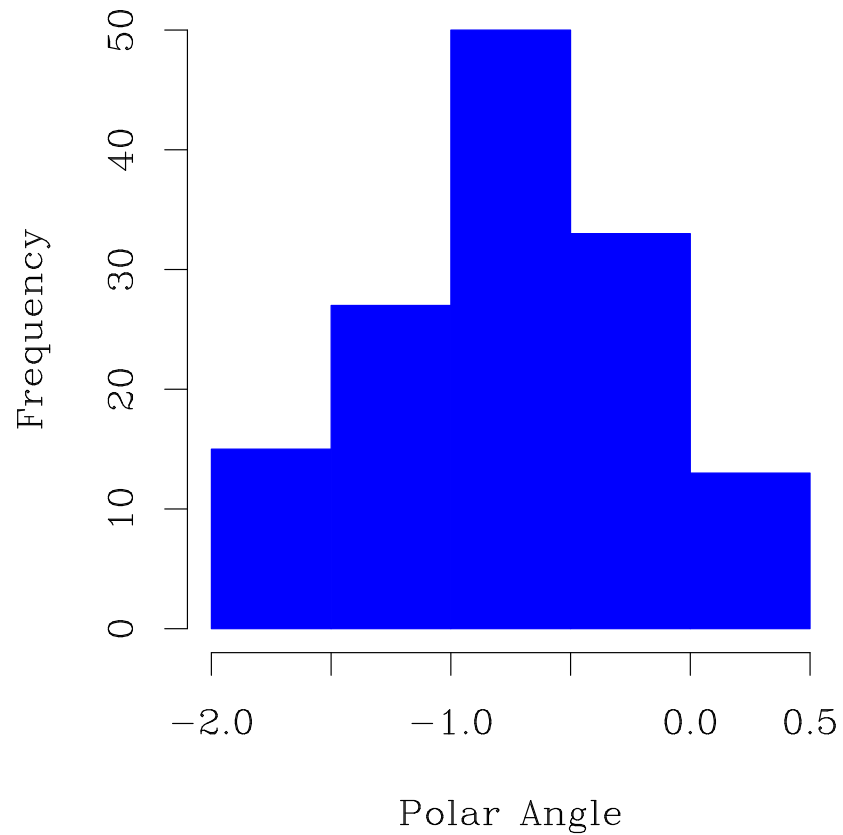
Estimate of Spectral Measure



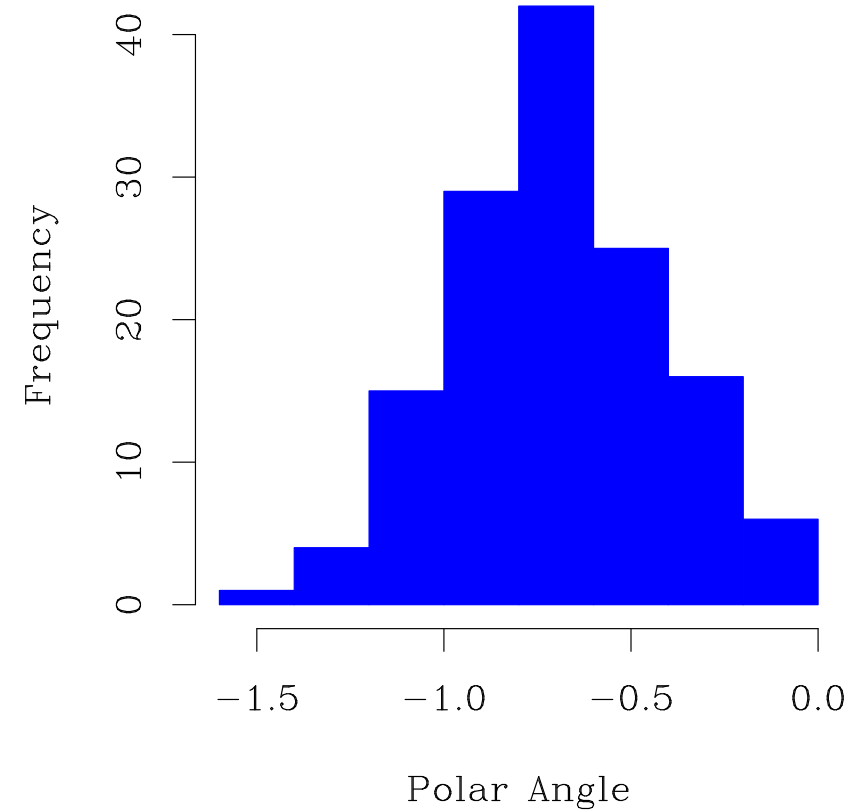
1. Set R , a large radius
2. Extremes are outside circle of radius R
3. Map extremes on the unit circle
4. Distribution of the angles

Examples of Spectral Measure

Stations 9 and 28



Stations 9 and 35



Building Blocks

Block 1: bivariate Gaussian

convenient computationally but not adequate for heavy tails

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Blocks 1 + 2 + 3: Bivariate hybrid Pareto distribution

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a bivariate Gaussian with **heavy tail** in a direction determined by an angle θ

Block 4: Mixture of Bivariate hybrid Pareto distribution

a discrete number of direction with heavy tails \Rightarrow mixture size

Extreme Value Theory

Goal : methods to analyze and characterize extreme events

Challenges :

- few observations are extreme
- estimate a risk which was never observed

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Extremes are defined as :

- Maxima : $M_n = \max\{Z_1, \dots, Z_n\}$
- Exceedances : Z_i such that $Z_i > u$

Two types of approaches

Block Maxima Approach

In theory : $M_n = \max\{Z_1, \dots, Z_n\}$, Z_i i.i.d. for large n

In practice : set a block size and take the maximum over each block

Typical example with daily data : block size = year
 \implies **annual maxima**

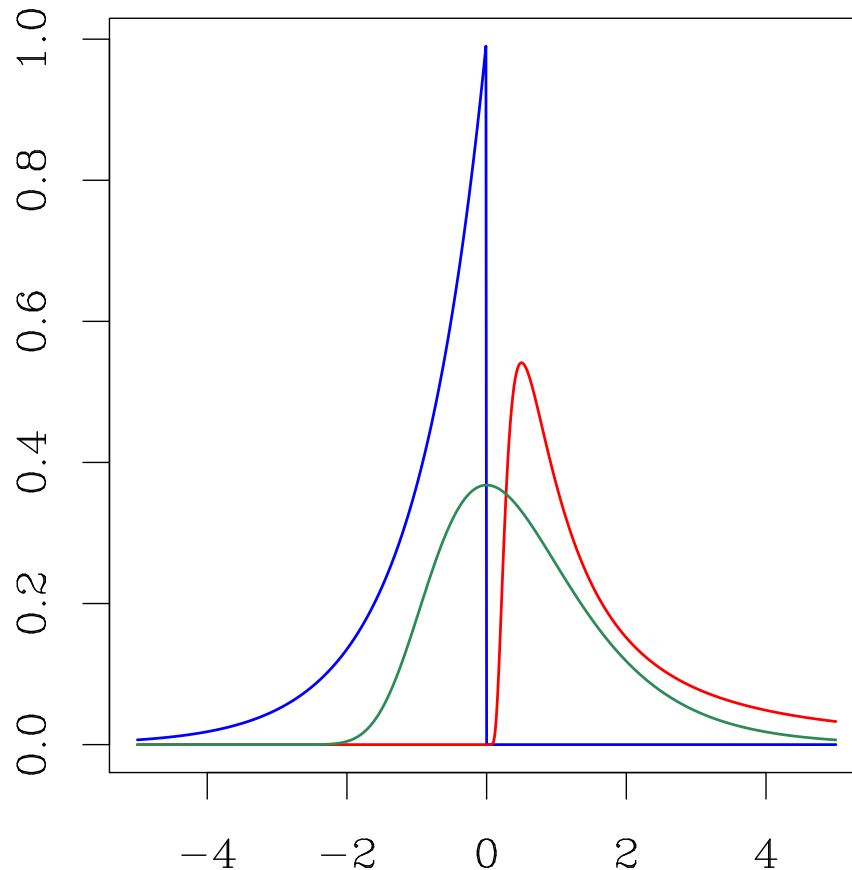
Return level :

What is the level u that the maximum runoff would exceed once in a 100 years?

$$P(M_n > u) = 1/100$$

Extreme Value Distributions

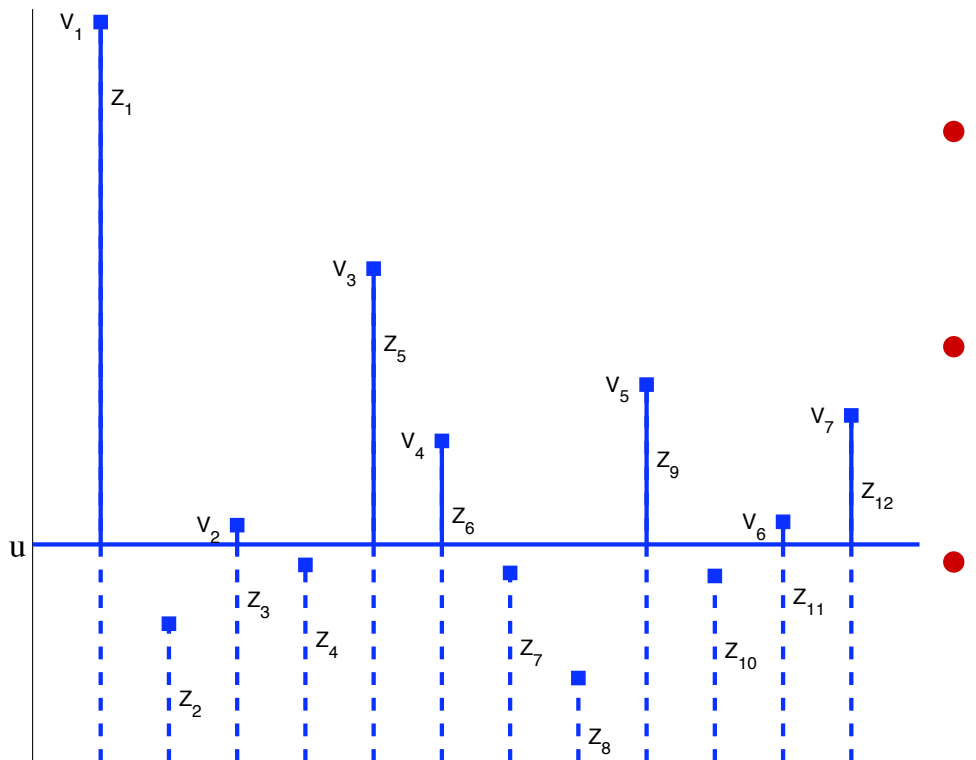
Maxima M_n , for large n , will behave either like



- Fréchet, heavy/Pareto tail:
Student t, Cauchy
- Gumbel, light/exponential tail:
Normal
- Weibull, finite tail: uniform

Peaks-over-Threshold

Excesses : $V_i = Z_i - u \mid Z_i > u$, u is a given threshold

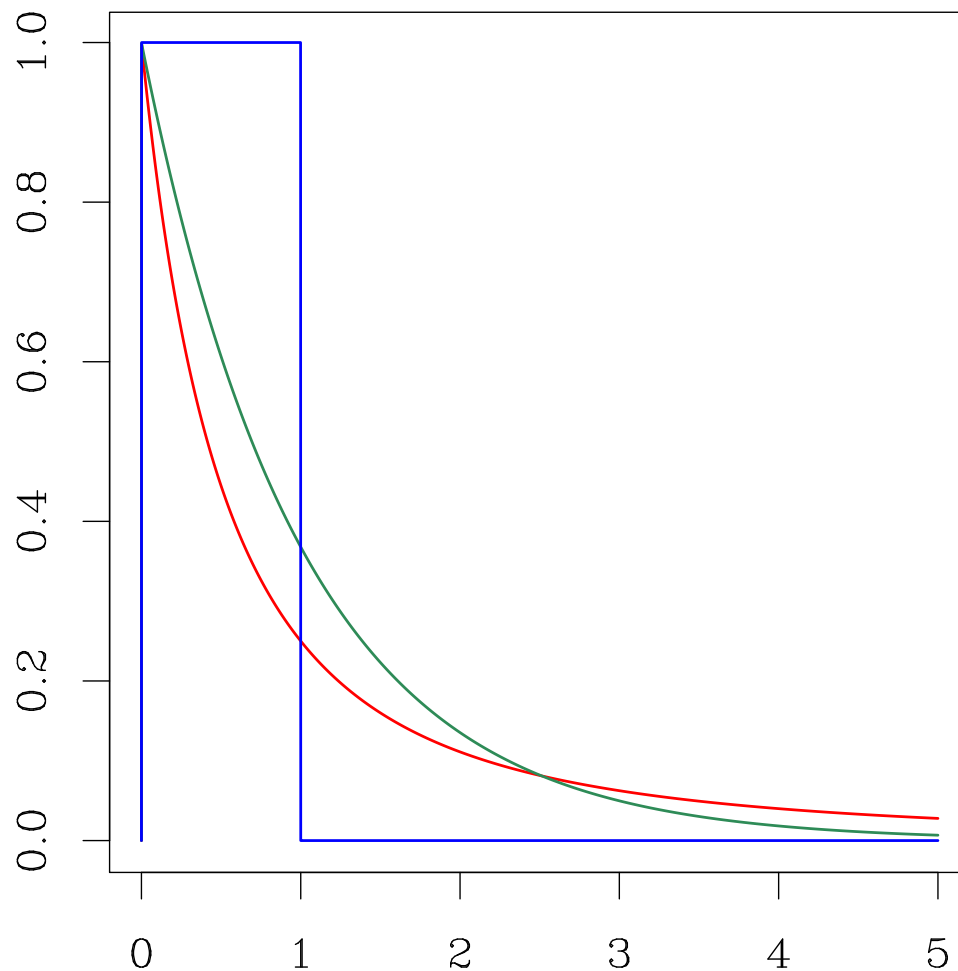


- Advantage : more data contribute to the estimation
- Difficulty : find a good threshold: bias / variance trade-off
- Questions on large events :

$$P(Z > u + \epsilon | Z > u)$$

Generalized Pareto Distribution

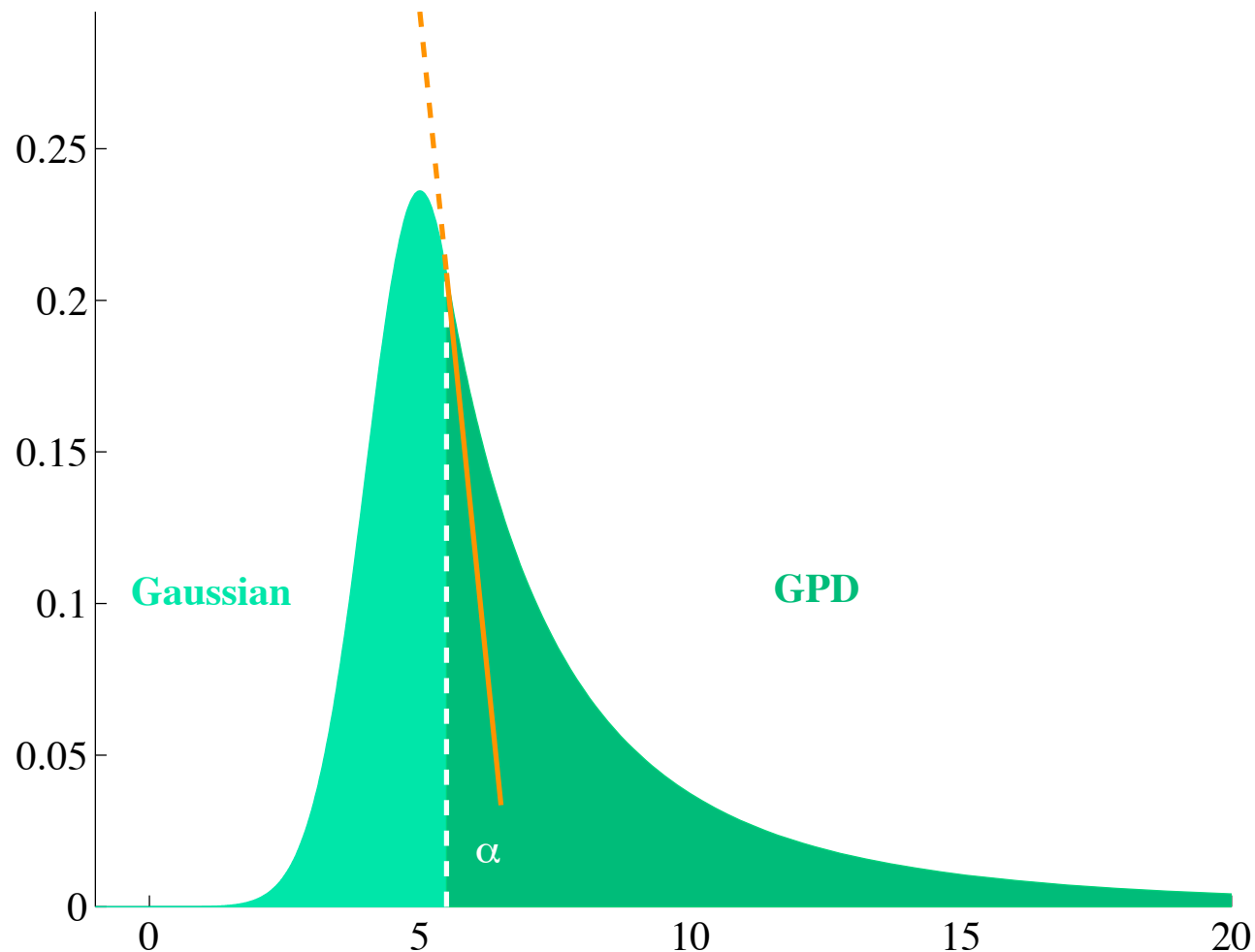
Excesses V_i , for large u will behave like a GPD with tail index ξ :



- $\xi > 0$, heavy/Pareto tail: Student t, Cauchy
- $\xi = 0$, light/exponential tail: Normal, Log-Normal, Gamma
- $\xi < 0$, finite tail: Uniform, Beta

Univariate Hybrid Pareto

Heavy-tailed distribution built by stitching together a Gaussian and a **Generalized Pareto** with continuity constraints



$h(\cdot; \xi, \mu_h, \sigma_h)$ **density**

ξ, β **GPD**

μ_h, σ_h **Gaussian**

α **junction point**

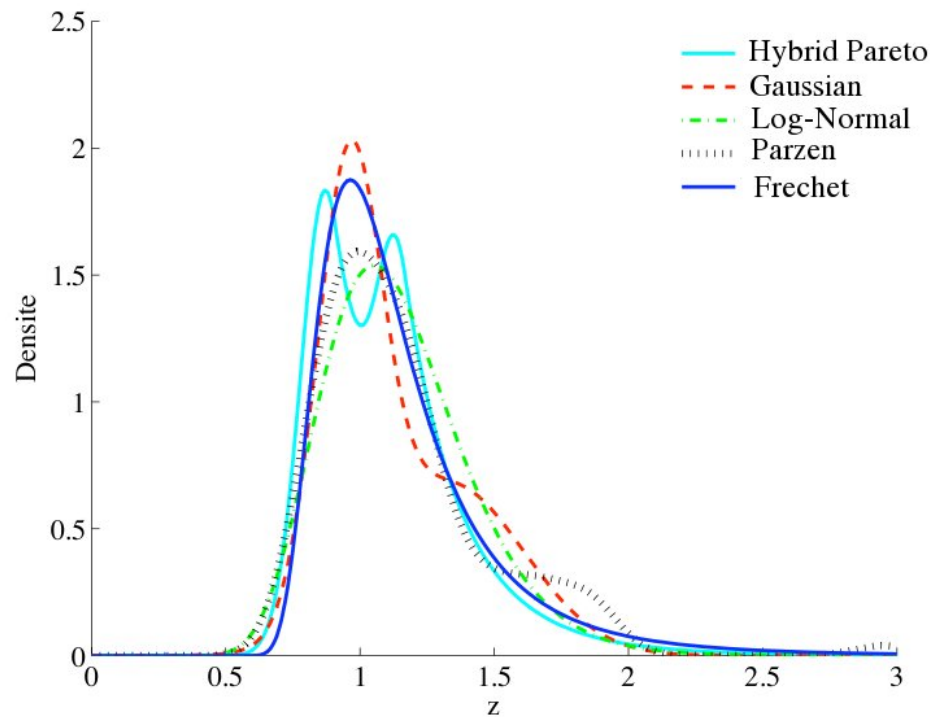
Modelling with the hybrid Pareto

★ Mixture of hybrid Paretos : univariate heavy tailed data

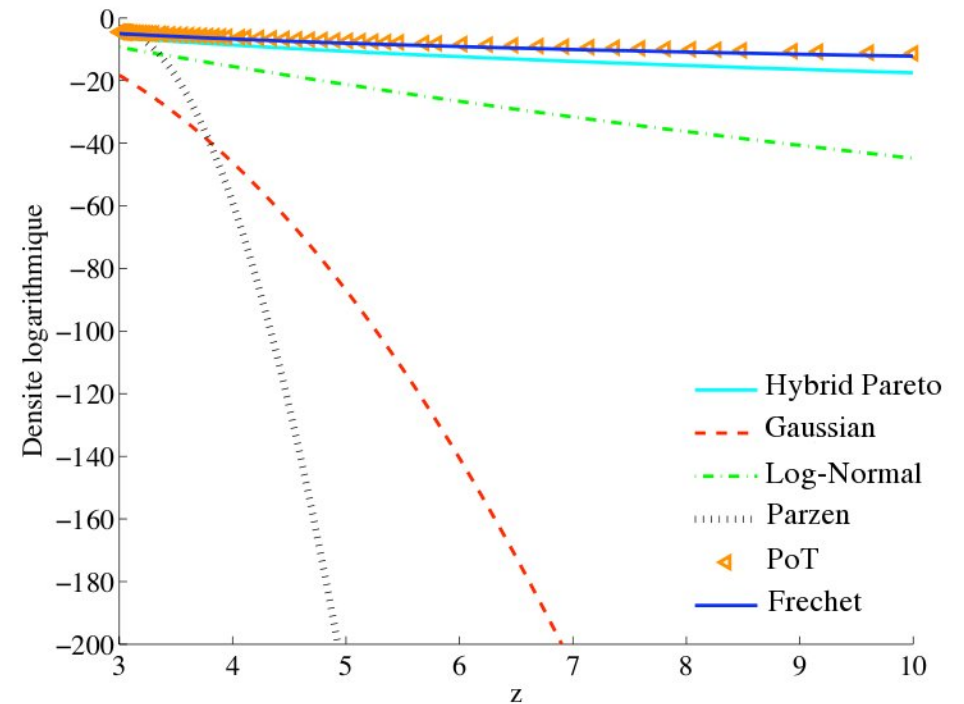
- **non parametric** in the central part: mixture of Gaussians
- **parametric** in the upper tail: combination of GPDs

Comparing Mixture Components

100 points from a Frechet distribution with $\xi = 0.2$



Central part



Upper tail

Modelling with the hybrid Pareto

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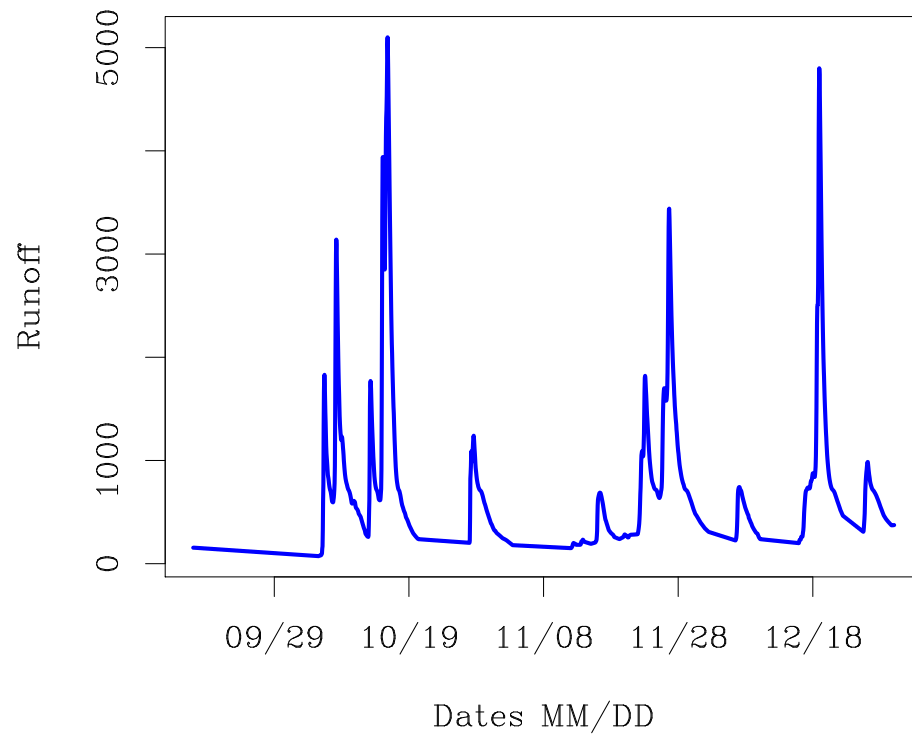
- **non parametric** in the central part: mixture of Gaussians
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★ Conditional mixture: parameters are functions of the input

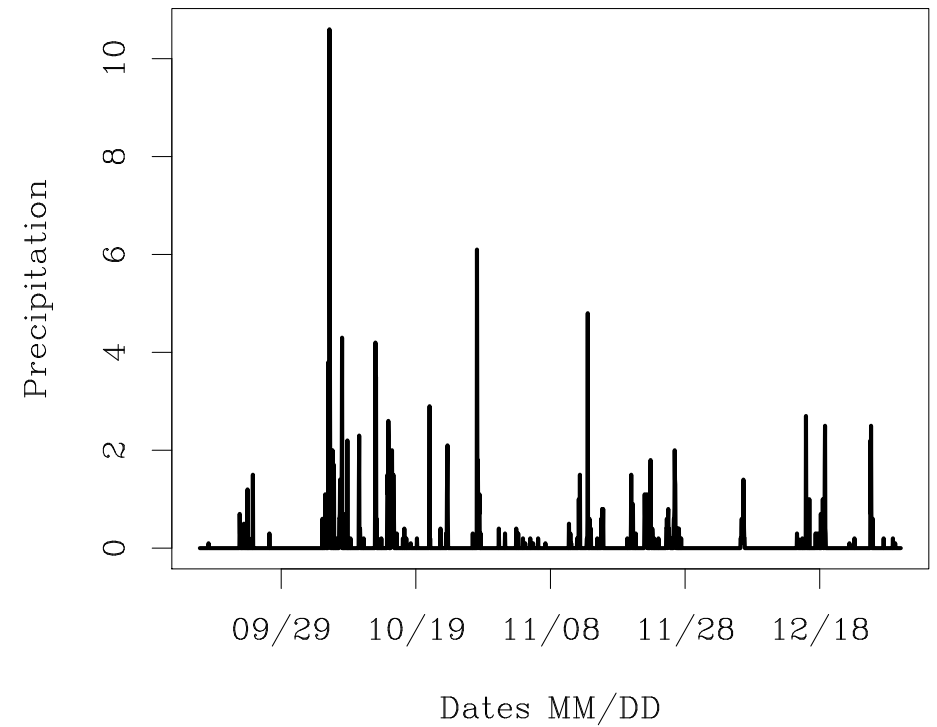
- **environmental application** : rainfall-runoff modelling
- **downscaling**: precipitation given large scale variables

Rainfall-Runoff process

Runoff



Rainfall



Projection Pursuit

1. Find a 1D projection which is interesting
interestingness could mean **heavy tails**

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2. Remove interestingness using a rotation trick

- **Rotate** to align the 1D projection with the x-axis
- **Gaussianize** by modelling with a univariate density along the x-axis
- **Rotate** back

Projection Pursuit

1. Find a 1D projection which is interesting

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Rotate, Gaussianize, Rotate back

3. Iterate steps 1 and 2

Stop when no more interesting 1D projection can be found

Projection Pursuit

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Stop when no more interesting 1D projection can be found

4. Model resulting density with a multivariate Gaussian

Combine the multivariate Gaussian with the 1D densities

Bivariate Hybrid Pareto Construction

Last steps of Projection Pursuit and reverse

4'. Start from a bivariate standard Gaussian :

assume no **interestingness** == **heavy tail** is present

Bivariate Hybrid Pareto Construction

Last steps of Projection Pursuit and reverse

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3'. Iterate once, i.e. apply steps 1 and 2 once

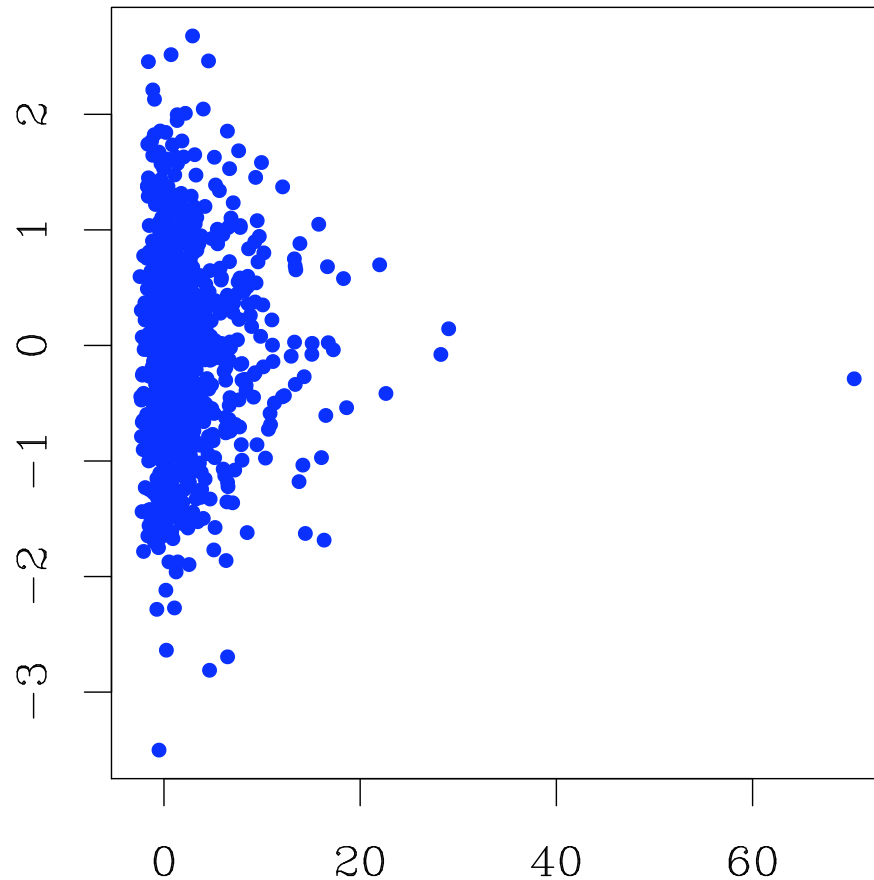
introduce interestingness in a **1D projection defined by an angle θ**

- Transform the density along the x-axis into a **heavy-tailed density**
- **Rotate back** to align heavy-tailed density with **angle θ**

Bivariate Hybrid Pareto Construction

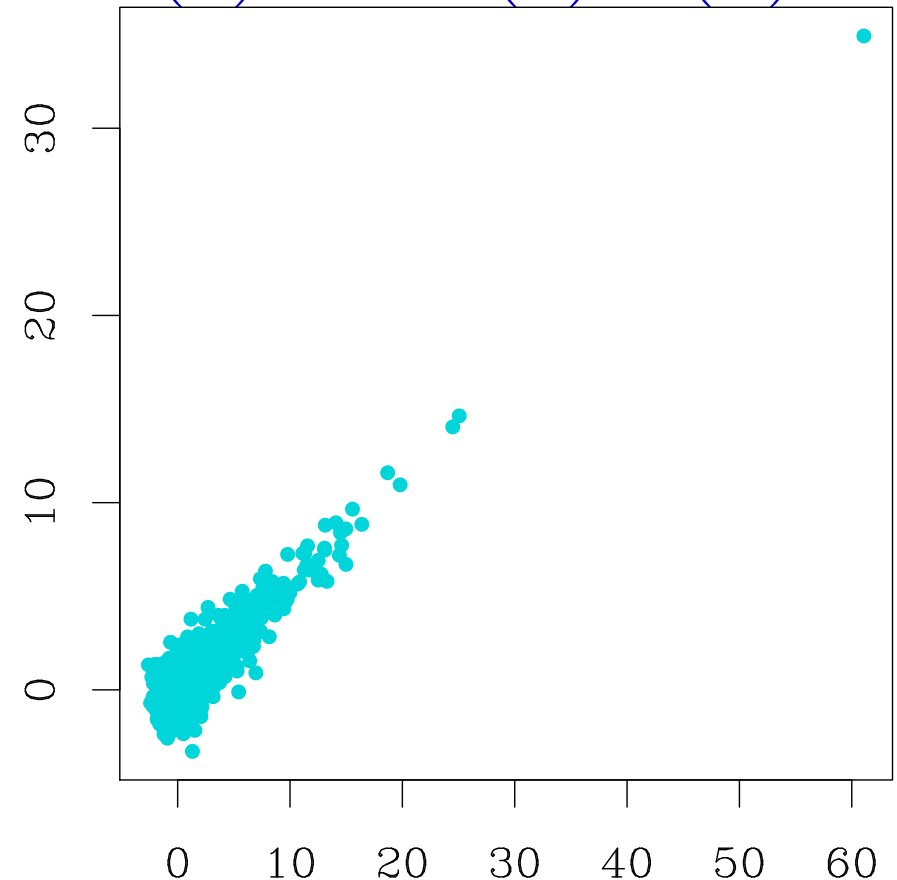
Independent random variables

$$\tilde{X} \rightarrow h(\cdot; \xi, 0, \sigma_h) \text{ and } \tilde{Y} \rightarrow \phi(\cdot; 0, \sigma)$$



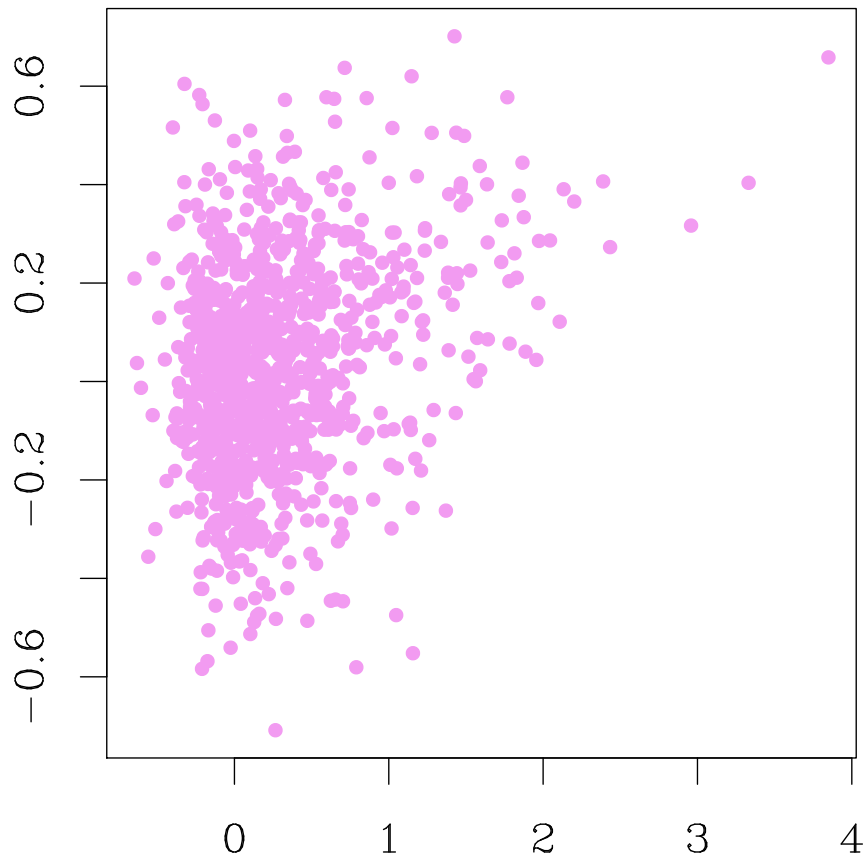
Rotation with angle $\theta \in [-\pi, \pi)$

$$\begin{pmatrix} X \\ Y \end{pmatrix} = R(\theta)^t \begin{pmatrix} \tilde{X} \\ \tilde{Y} \end{pmatrix} + \begin{pmatrix} \mu_1 \\ \mu_2 \end{pmatrix}$$

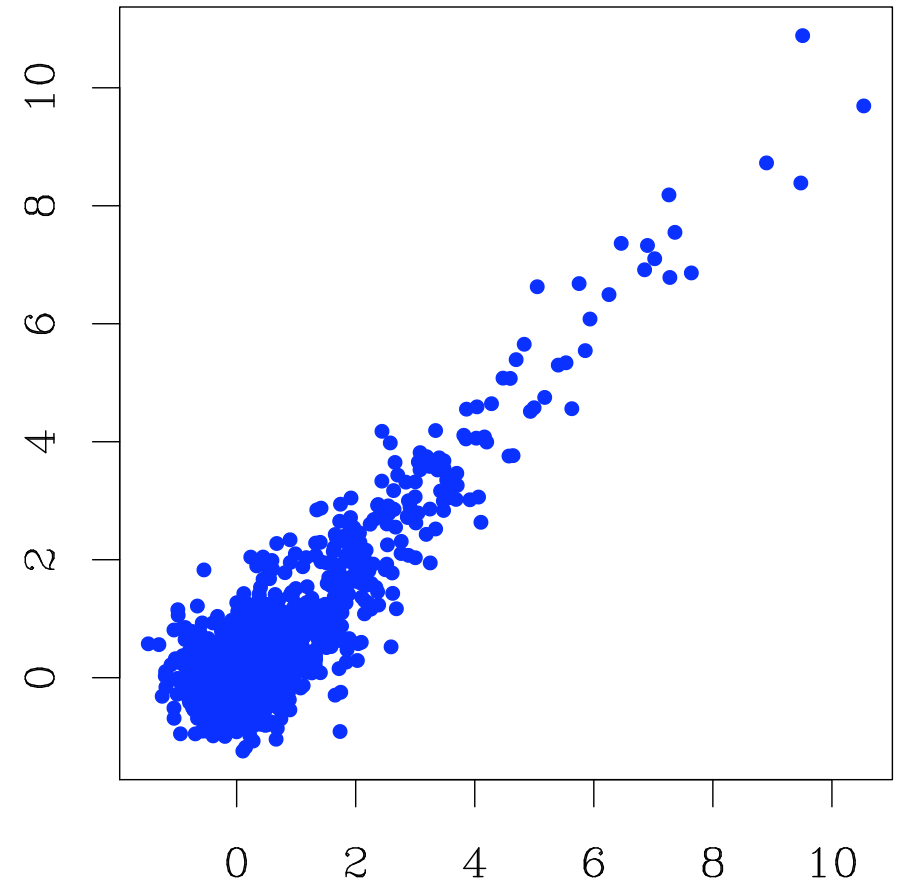


Sample from Bivariate Hybrid Paretos

$\theta = -\pi/24$ and $\xi = 0.001$



$\theta = -\pi/4$ and $\xi = 0.2$



Density of the Bivariate Hybrid Pareto

According to the PP construction :

$$h_2(x, y; \psi) = \phi_2(x, y) \frac{h(p_\theta(x, y))}{\phi(p_\theta^\perp(x, y))}$$

★ h and ϕ are the densities of the hybrid Pareto and the standard Gaussian respectively

★ p_θ and p_θ^\perp are the projections along the line defined by θ and the line orthogonal to it

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★ **The density of the bivariate hybrid decomposes into**

$$h_2(x, y; \psi) = \underbrace{h(p_\theta(x - \mu_1, y - \mu_2); \xi, \sigma^{(h)})}_{\text{hybrid Pareto}} \underbrace{\phi(p_\theta^\perp(x - \mu_1, y - \mu_2)/\sigma)}_{\text{Gaussian}}$$

★ $\psi = (\mu_1, \mu_2, \sigma, \theta, \xi, \sigma^{(h)})$ is the bivariate hybrid Pareto parameter vector

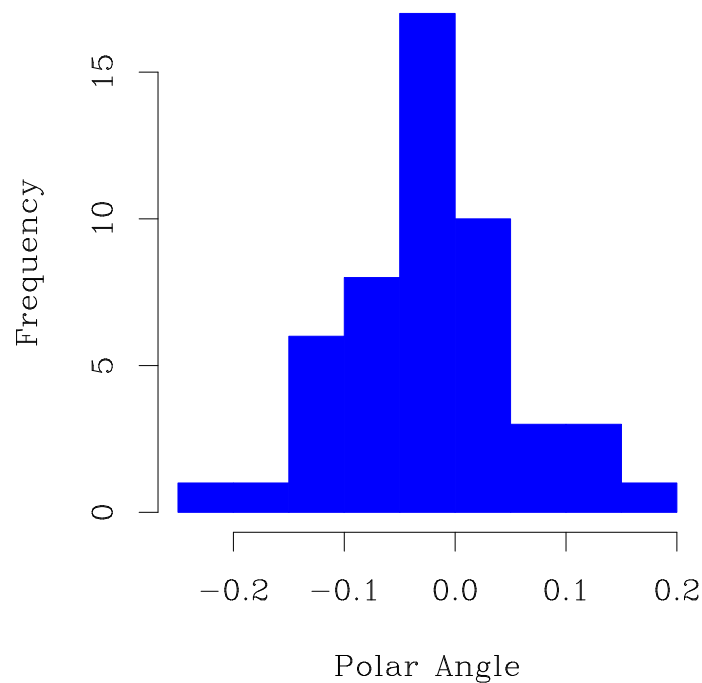
Rotation and Dependence

★ Rotation transforms the covariance matrix : $R(\theta)\Sigma R(\theta)^t$

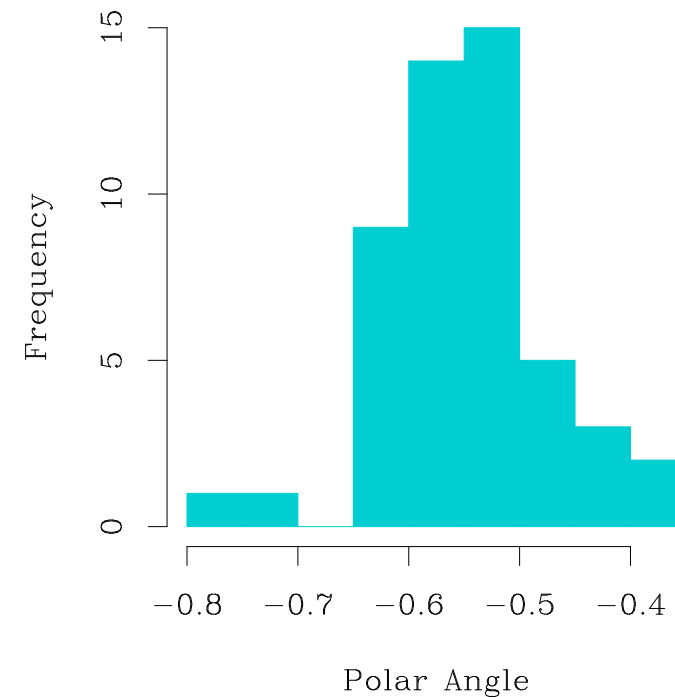
Rotation and Dependence

- ★ Rotation transforms the covariance matrix : $R(\theta)\Sigma R(\theta)^t$
- ★ Rotation introduces **dependence in the extremes** as well

Polar angle corresponding to large radius



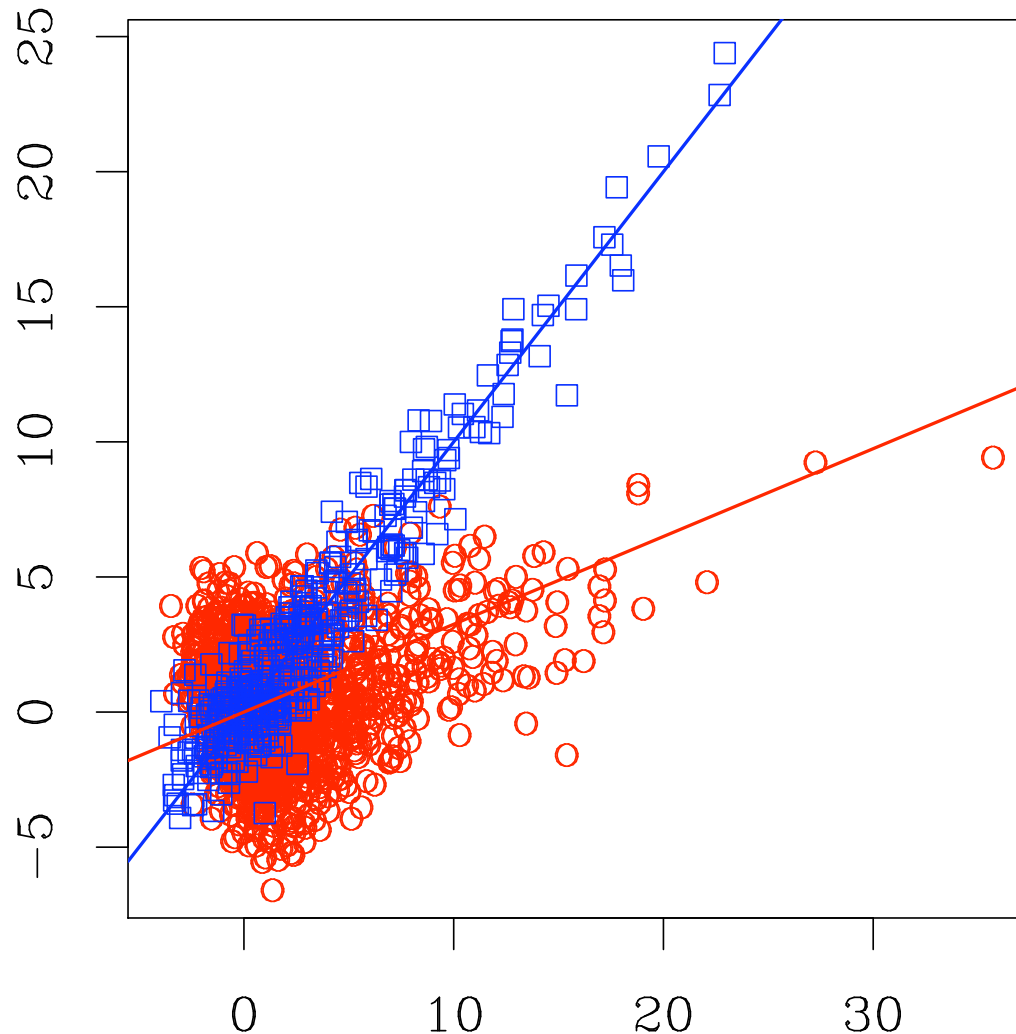
Independence $\theta = 0$



Dependence $\theta \neq 0$

Directions of Extremes in the Mixture

$$P(\|(X, Y)\| > R, S = j) = P(\|(X, Y)\| > R | S = j)P(S = j) \approx \frac{\pi_j}{\gamma} \left(\frac{\xi}{\beta_j}\right)^{-1/\xi} R^{-1/\xi}$$



$$P(\theta = \theta_j) \propto \pi_j (\sigma_j^{(h)})^{1/\xi}$$

- Same tail index: $\xi_j = \xi \quad \forall j$
- π_j is the mixture weight

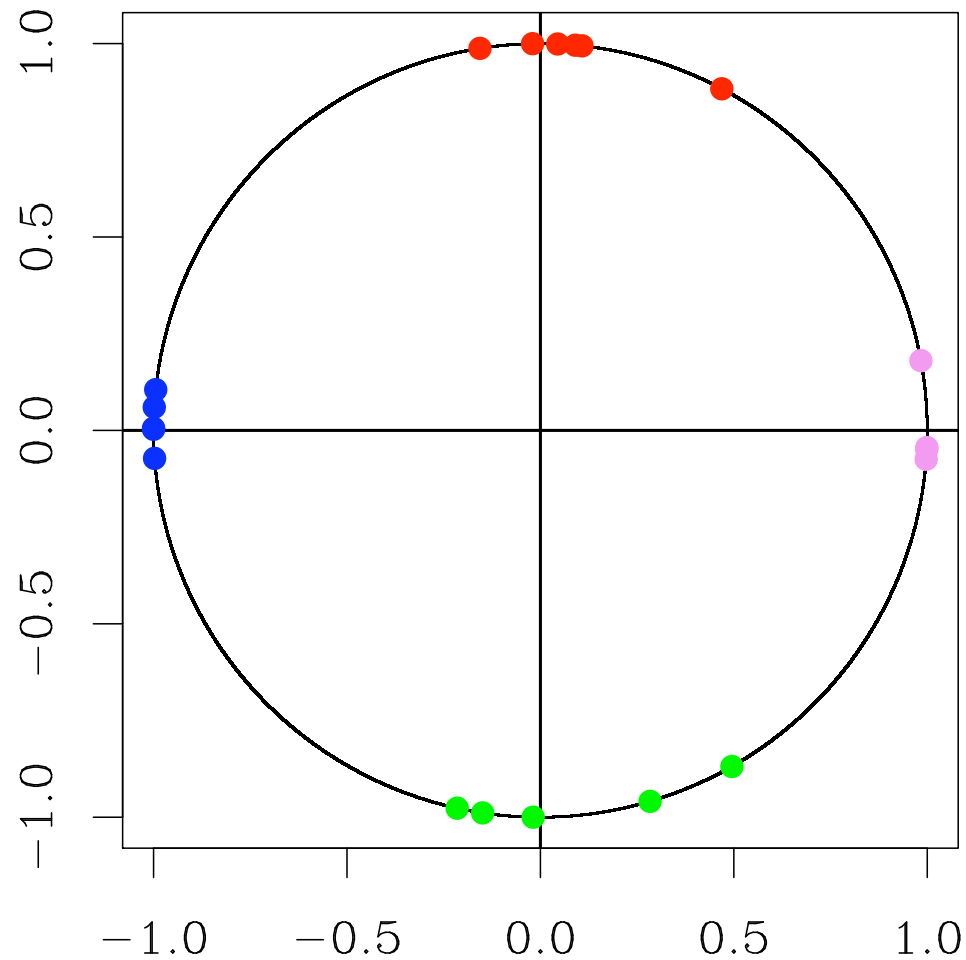
Initialize θ_j

Angle Clustering : Find good extremal directions

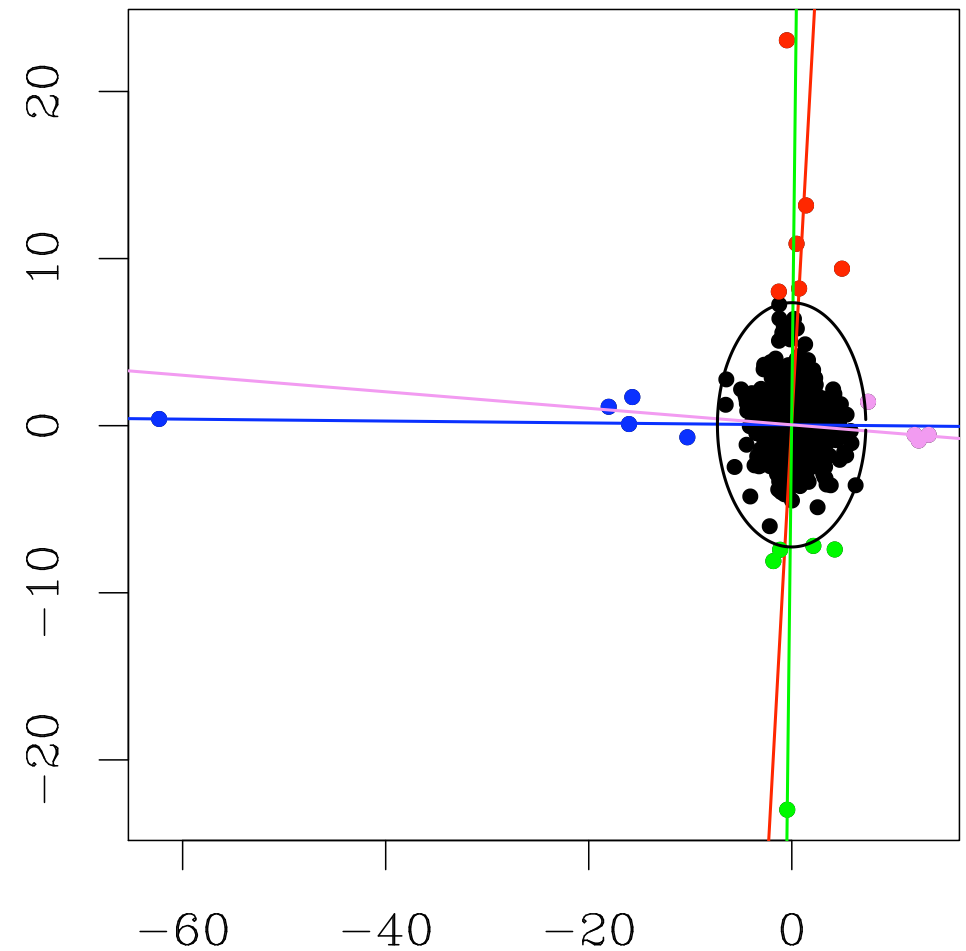
- a) Center and sphere the data
- b) Transform into polar coordinates: $R \in \mathbb{R}^+$ and $\omega \in [-\pi, \pi)$
- c) Consider ω such that $R > u$
- d) Compute **circular distances**
- e) Perform **clustering** and cluster centers are taken as initial angles

Independent Bivariate α -stable Data

Angle Clustering

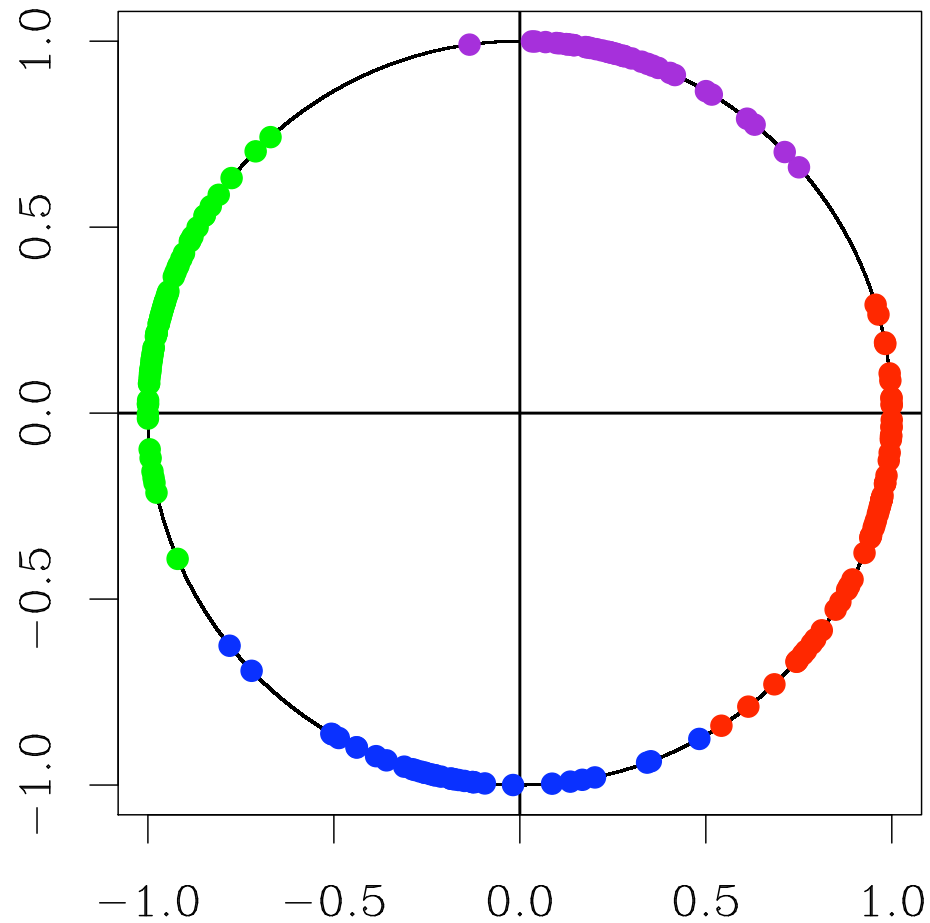


1D projections

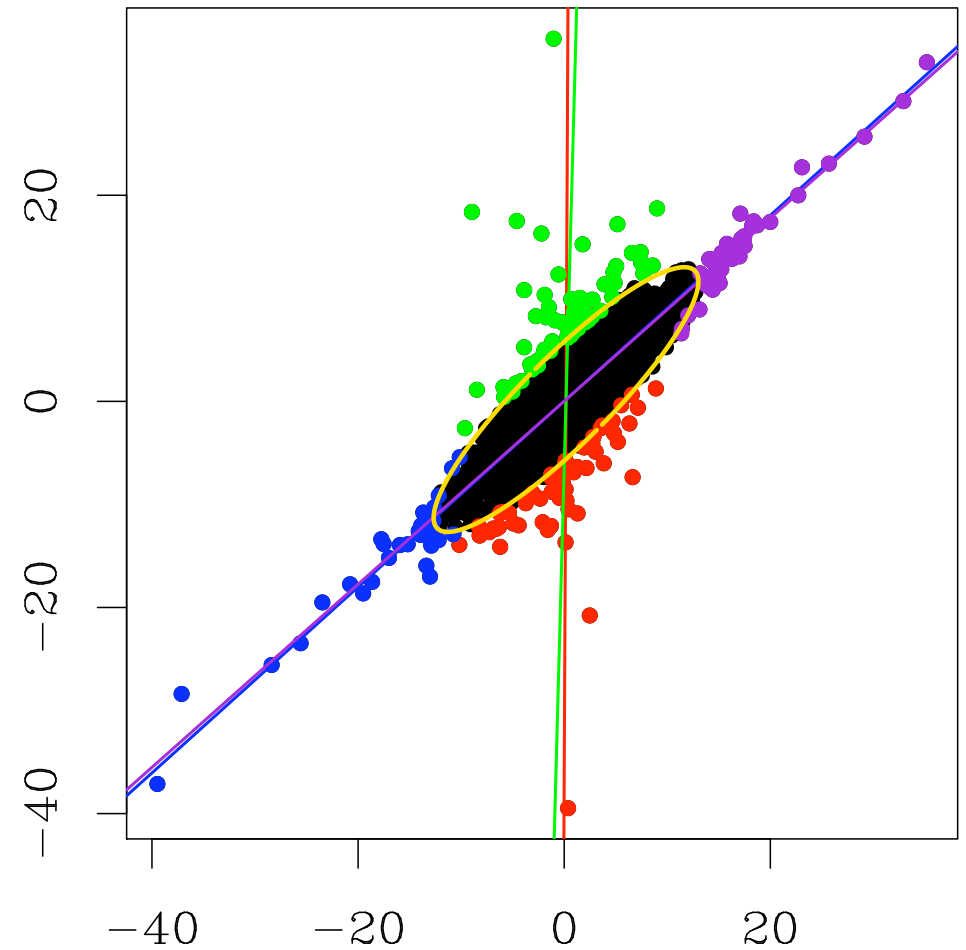


AR(1) with Student t Noise

Angle Clustering



1D projections



Mixture Initialization

1. Estimate the rotation angles θ_j

★ **Clustering** of angles corresponding to large radius

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2. Iterative classification

- ★ **Decrease the threshold** used for angle estimation
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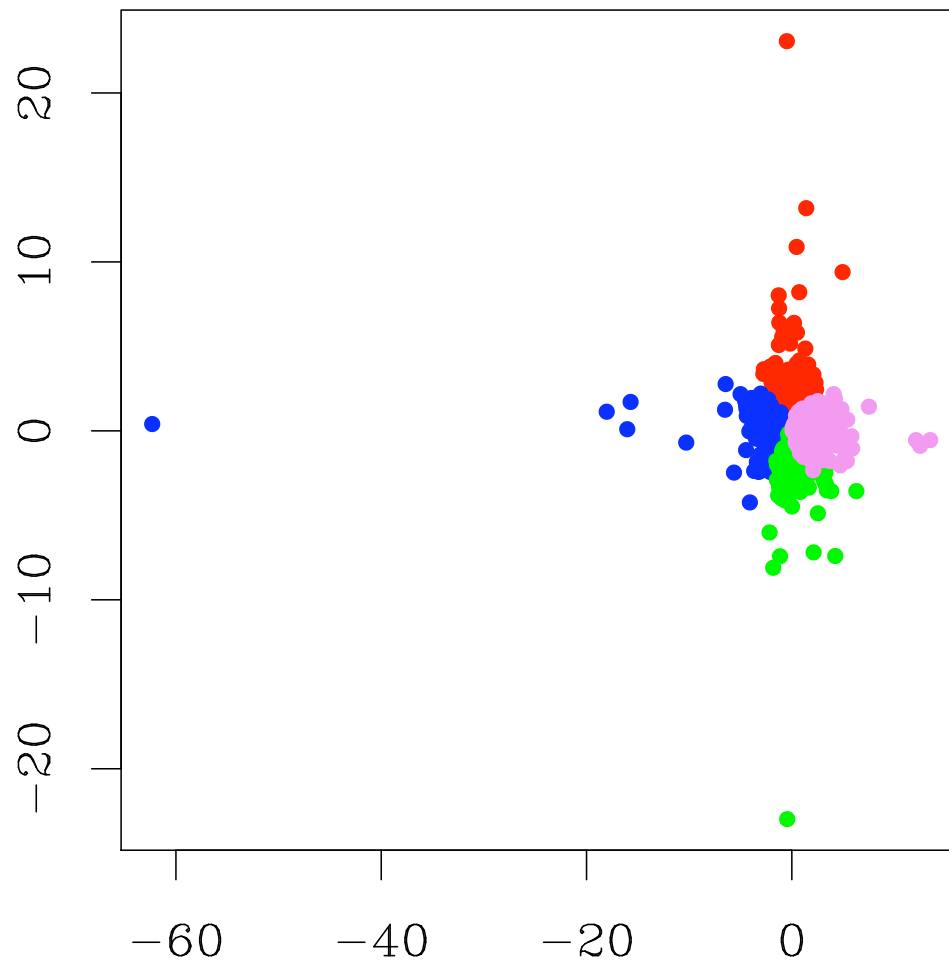
- ★ **Decrease the threshold** used for angle estimation
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3. Initialize one component per cluster

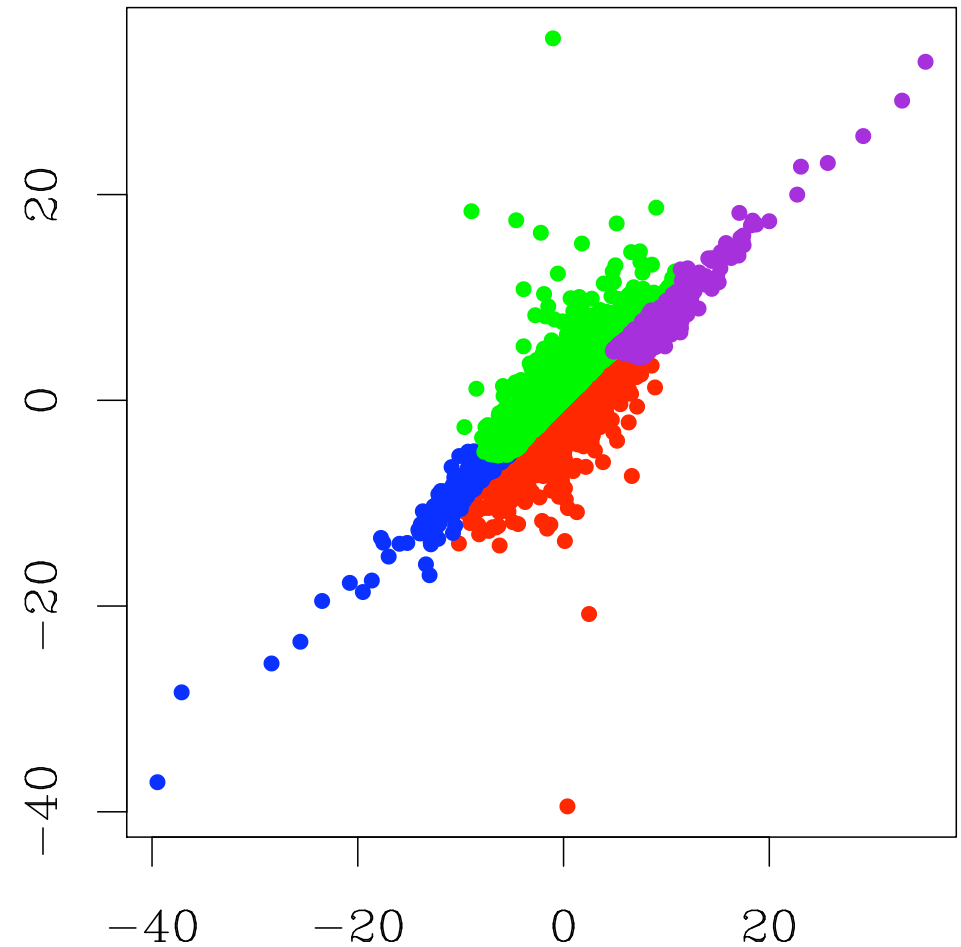
- ★ **Estimate univariate density parameters** on projected data

Iterative Clustering

Independent Bivariate α -stable
Data



AR(1) with Student t Noise



GEM for the Bivariate Mixture

$\sum_{j=1}^m \pi_j h_2(x, y; \psi_j)$, with $h_2(\cdot, \cdot; \psi_j)$ the bivariate hybrid pareto density

$\{\pi_j, \psi_j\}_{j=1:m}$ are estimated by **maximizing the log-likelihood**

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Generalized EM algorithm:

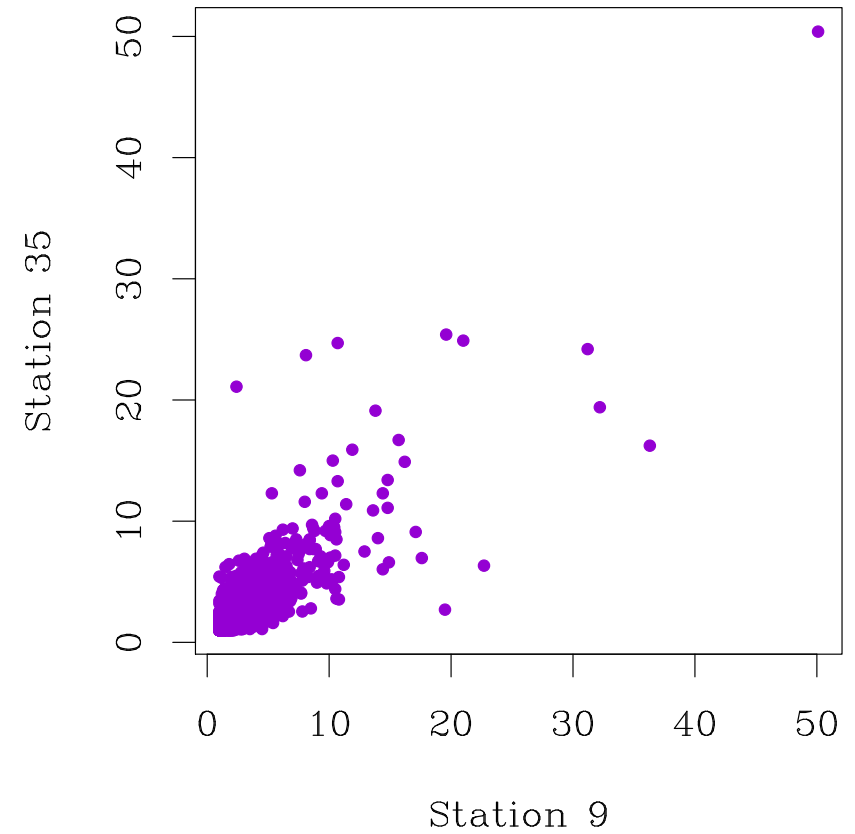
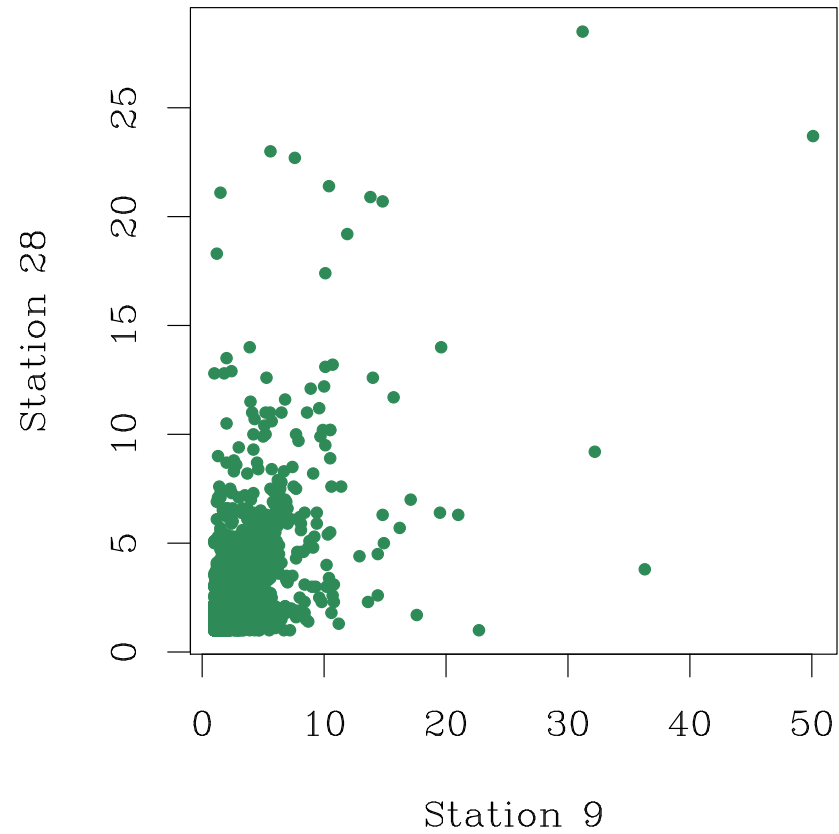
E-step: compute posteriors $\tau_{i,j}$ according to current parameters

M-step:

1. Update the priors $\pi_j = 1/n \sum_{i=1}^n \tau_{i,j}$
2. For each j , optimize numerically w/r to ψ_j :

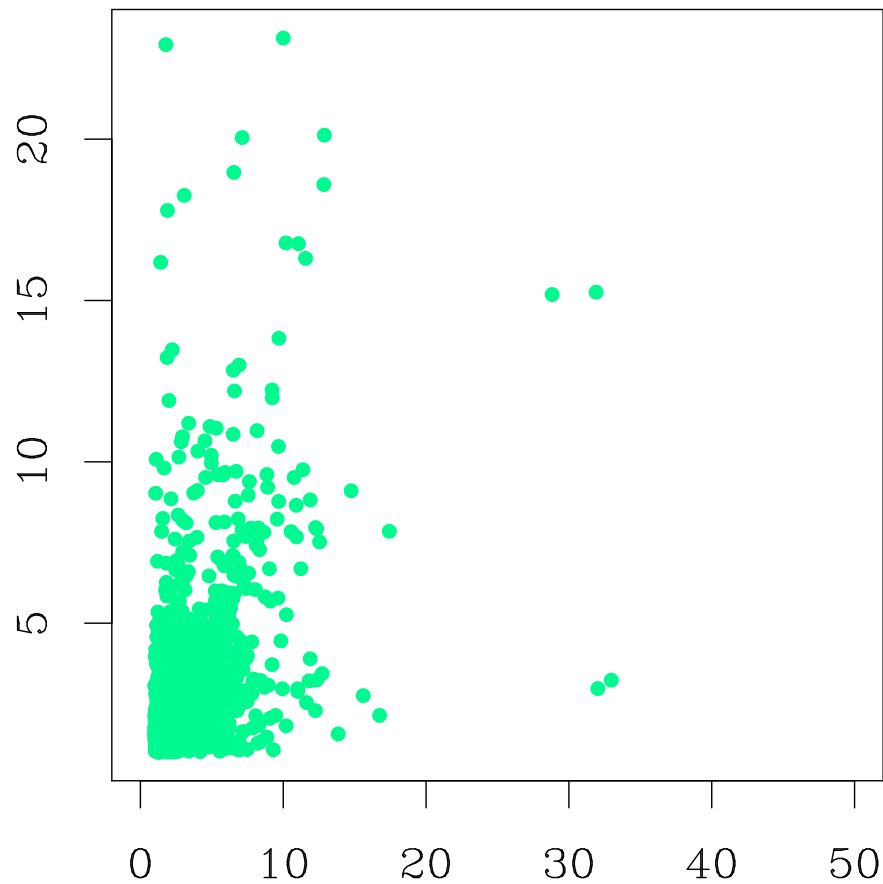
$$\sum_{i=1}^n \tau_{i,j} \log (h_2(x_i, y_i; \psi_j))$$

Precipitation

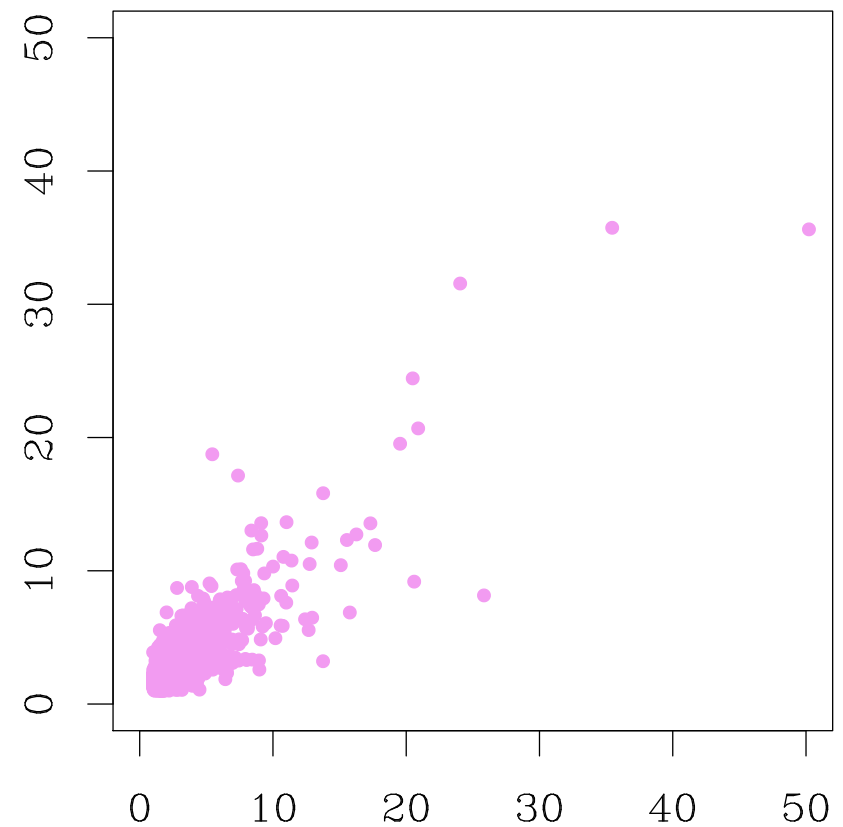


Data generated from the trained model

Trained on data from stations
9 and 28

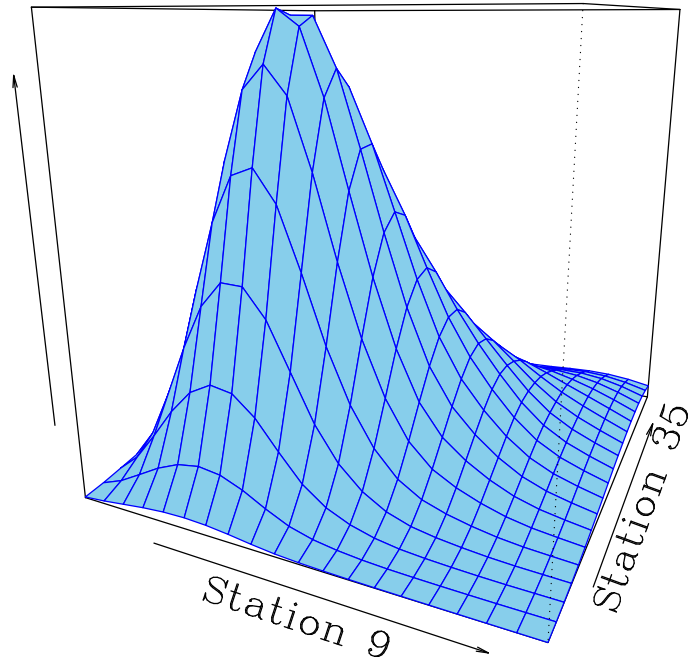


Trained on data from stations
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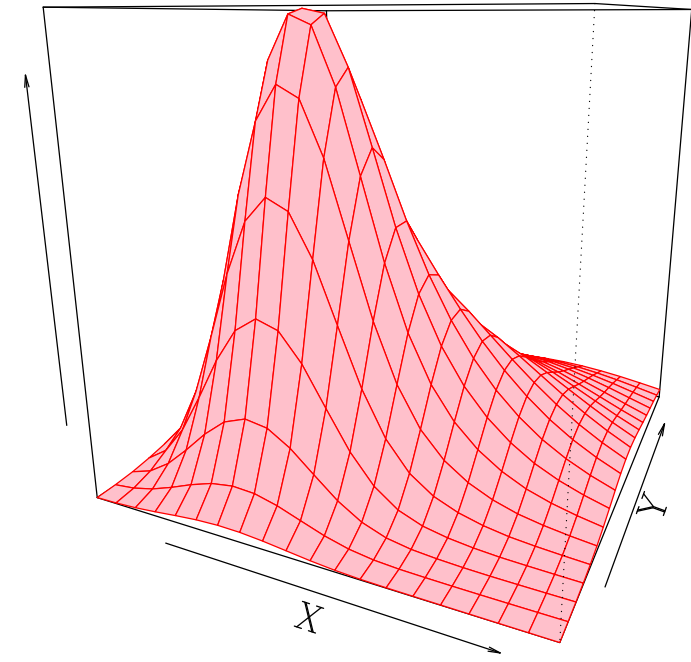


Full Density Estimate

Stations 9 and 35



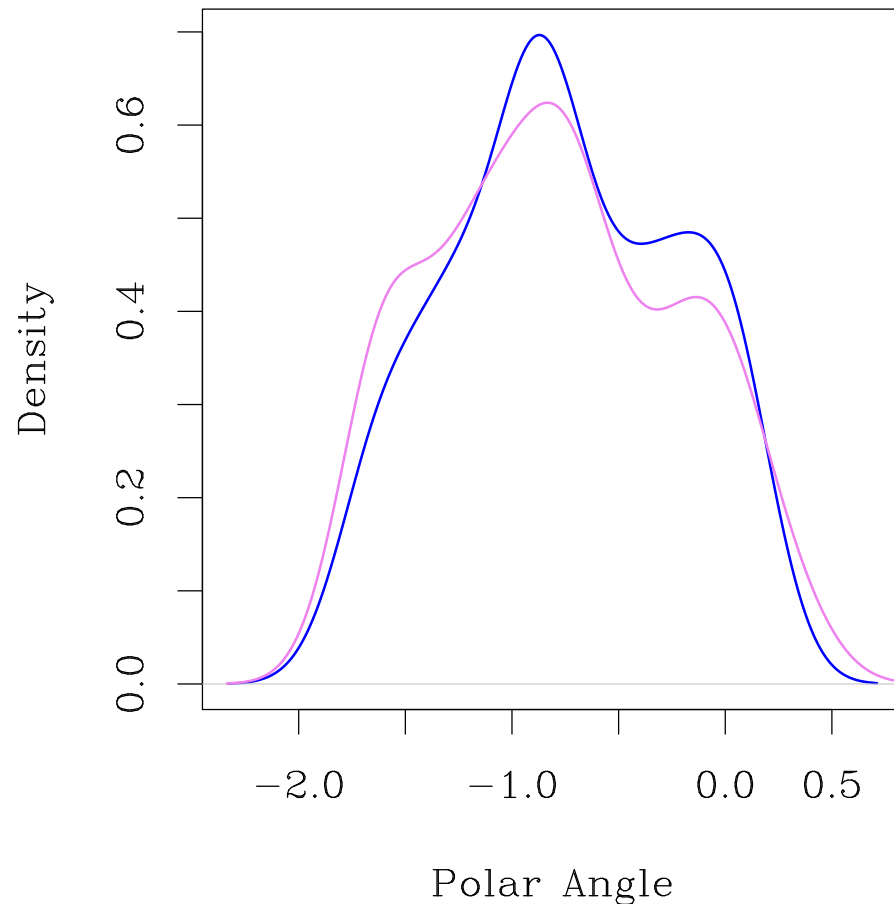
Trained mixture



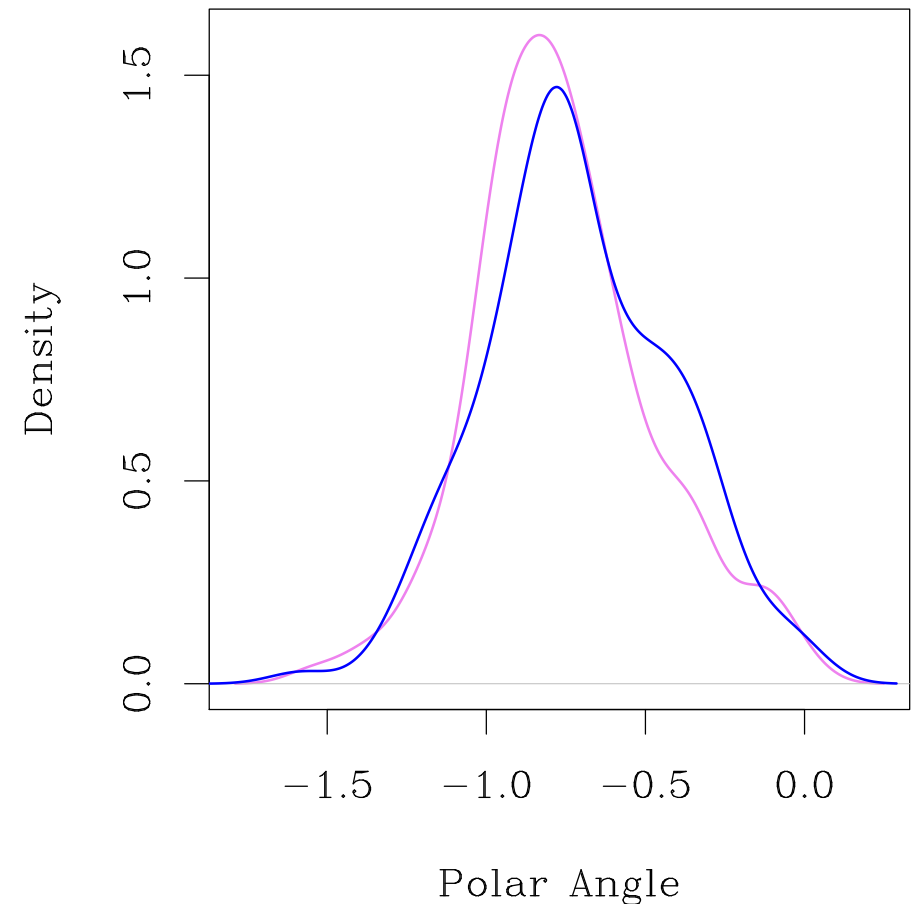
Kernel Estimates of the Angular Spread

Precipitation data versus Trained Mixture

Stations 9 and 28



Stations 9 and 35



Next Steps

- ✦ Introduce **multivariate Gaussian** components to model the central part
- ✦ Automated **model selection**: number of components
- ✦ Higher dimensions...

References

- [1] Carreau J. and Bengio Y. (2009) **A Hybrid Pareto Model for Asymmetric Fat-tailed Data: the Univariate Case**, *Extremes*, Vol. 12, 53-76.
- [2] Friedman, J. H. (1987) **Exploratory Projection Pursuit**, *JASA*, Vol. 82, 249-266.
- [3] Chen, S. S. and Gopinath, R. A. (2001) **Gaussianization**, *NIPS*, Vol. 13.
- [4] Coles, S., Heffernan J. and Tawn J. (1999) **Dependence measures for extreme value analysis**, *Extremes*, Vol. 2, 339-365