

On the estimation of the second order parameter in extreme-value theory

by

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- 1 Extreme-Value Theory
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Exemples of Applications

- Historically : meteorological events (rains, winds....).
- Finance : stock market crash and financial crises.
- Reinsurance.
- Aviation.
- Biology : Epidemiology, security food.

Main results on extreme value theory

Let X_1, \dots, X_n be a sequence of independent copies of a real random variable (r.v.) X with **cumulative distribution function** F . The order statistics associated to this sample are denoted by :

$$X_{1,n} \leq \dots \leq X_{n,n}.$$

Fisher-Tippett-Gnedenko theorem

Under some conditions of regularity on F , there exists a real parameter γ and two sequences $(a_n)_{n \geq 1} > 0$ and $(b_n)_{n \geq 1} \in \mathbb{R}$ such that for all $x \in \mathbb{R}$,

$$\lim_{n \rightarrow \infty} \mathbb{P} (a_n^{-1}(X_{n,n} - b_n) \leq x) = EV_\gamma(x),$$

$$\text{with } EV_\gamma(x) = \begin{cases} \exp \left(-(1 + \gamma x)_+^{-1/\gamma} \right) & \text{if } \gamma \neq 0, \\ \exp(-e^{-x}) & \text{if } \gamma = 0, \end{cases}$$

where $y_+ = \max(y, 0)$.

Definition

- ◇ The parameter γ is the tail index, the primary parameter of extreme events.
- ◇ EV_γ is called the extreme value distribution and F is then said to belong to the domain of attraction of EV_γ ($F \in DA(EV_\gamma)$).

Heavy-tailed model

- ◇ In **statistics of Extremes**, a model F is said to be heavy-tailed whenever, for some $\gamma > 0$, its survival function is of the forme :

$$1 - F(x) = x^{-1/\gamma} l_F(x) \Leftrightarrow \mathbb{U}(x) = x^\gamma l_{\mathbb{U}}(x)$$

where $\mathbb{U}(x) = \inf\{y : F(y) \geq 1 - 1/x\}$ and $l_\bullet(\cdot)$ is a **slowly varying function** i.e. $l_\bullet(\lambda x)/l_\bullet(x) \rightarrow 1$ as $x \rightarrow \infty$ for all $\lambda \geq 1$.

The present model is now often restated as the assumption of F regular variation at infinity with index $-1/\gamma$ (denoted $1 - F(x) \in RV_{-1/\gamma}$).

Inference statistic of γ for heavy-tailed model

In Statistics of extremes, inference is often based

$$\diamond W_{i,k} = (\log X_{n-i+1,n} - \log X_{n-k,n}) \quad \text{the log-excesses}$$

$$\diamond Z_{i,k} = i (\log X_{n-i+1,n} - \log X_{n-i,n}) \quad \text{the rescaled log-spacings}$$

Exemple of γ estimator

- $H_{n,k} = \frac{1}{k} \sum_{i=1}^k W_{i,k} = \frac{1}{k} \sum_{i=1}^k Z_{i,k}$, Hill Estimator Hill (1975)
- $\mathcal{M}_{n,k}^\alpha = \frac{1}{k} \sum_{i=1}^k W_{i,k}^\alpha$, Moment Estimator, Deker et al (1989)
- $\mathcal{W}_{n,k} = \frac{1}{k} \sum_{i=1}^k W\left(\frac{i}{k+1}\right) Z_{i,k}$, Kernel estimator of γ ,
 W is a positive Kernel function .
- $\mathcal{S}_{n,k} = \frac{1}{k} \sum_{j=1}^k G_\alpha\left(\frac{i}{k+1}\right) W_{i,k}^\alpha$, G_α is a positive weight
function and α a positive real number.

Second Order Condition

The asymptotic distribution of estimators of γ is obtained under a **second order condition**.

Second Order Condition (S.O.C)

There exist a function $A(x) \rightarrow 0$ and a **second order parameter** $\rho \leq 0$ such that, for every $\lambda > 0$,

$$\lim_{x \rightarrow \infty} \frac{\log U(\lambda x) - \log U(x) - \gamma \log \lambda}{A(x)} = K_\rho(\lambda),$$

where $K_\rho(\lambda) = \int_1^\lambda u^{\rho-1} du$.

Remarks

- $|A|$ is regularly varying with index ρ .
- If ρ decreases, the rate of convergence of $\log U(tx) - \log U(t)$ to $\gamma \log$ increases.
- ρ controls the bias of the estimators of γ .
- A **third order condition** is needed to deal with the asymptotic distribution of ρ estimators.

Third Order Condition

Third Order Condition (T.O.C)

There exist functions $A(x) \rightarrow 0$ and $B(x) \rightarrow 0$, a second order parameter $\rho \leq 0$ and a third order parameter $\beta \leq 0$ such that, for every $\lambda > 0$,

$$\lim_{x \rightarrow \infty} \frac{(\log U(\lambda x) - \log U(x) - \gamma \log \lambda)/A(x) - K_\rho(\lambda)}{B(x)} = L_{\rho, \beta}(\lambda),$$

where

$$L_{(\rho, \beta)}(\lambda) = \int_1^\lambda s^{\rho-1} \int_1^s u^{\beta-1} du ds,$$

and the functions $|A|$ and $|B|$ are regularly varying with index ρ and β respectively.

Objective

Propose a new class of estimators for the second order parameter and to study their asymptotic properties.

New family of estimators for the second order parameter

The model

- $T_n = T_n(X_1, \dots, X_n)$: a random vector in \mathbb{R}^d drawn from the sample X_1, \dots, X_n .
- The statistics can always be expanded as :

$$\omega_n^{-1}(T_n - \chi_n \mathbb{I}) \xrightarrow{\mathbb{P}} f(\rho)$$

where

- $\mathbb{I} = {}^t(1, \dots, 1) \in \mathbb{R}^d$,
- χ_n and ω_n : random variables,
- $\xi_n \in \mathbb{R}^d$: a random vector,
- $f: \mathbb{R}^- \rightarrow \mathbb{R}^d$: a function continuously differentiable in a neighborhood of ρ (independent of γ).

General approach

Notations

$\psi : \mathbb{R}^d \rightarrow \mathbb{R}$ such that

◇ Invariance properties (Inv-prop)

$\psi(x + \lambda \mathbb{I}) = \psi(x)$ for all $x \in \mathbb{R}^d$ and $\lambda \in \mathbb{R}$,

$\psi(\lambda x) = \psi(x)$ for all $\lambda \in \mathbb{R} \setminus \{0\}$,

◇ Regularity properties (Reg-prop)

ψ is continuously differentiable in a neighborhood of $f(\rho)$,

$\varphi := \psi \circ f$ is continuous in a neighborhood of ρ

◇ Bijection property (Bij-prop)

there exist $J_0 \subseteq \mathbb{R}^-$ and an open interval $J \subset \mathbb{R}$ such that φ is a bijection from J_0 to J .

The estimator

Clearly

- by the invariance and the regularity properties
 - ◊ $\psi(\omega_n^{-1}(T_n - \chi_n \mathbb{I})) = \psi(T_n) \xrightarrow{\mathbb{P}} \psi(f(\rho)).$
 - ◊ $Z_n = \psi(T_n) \approx \varphi(\rho).$
- Under the bijection property, our family of estimators of the second order parameter is thus defined by :

$$\hat{\rho}_n = \varphi^{-1}(Z_n) \mathbb{1}\{Z_n \in J\}.$$

$\mathbb{1}_A$ is the indicator function of the set A

Asymptotic properties

Theorems

Suppose that **Inv-prop**, **Reg-prop** and **Bij-prop** hold then

- $\hat{\rho}_n \xrightarrow{\mathbb{P}} \rho$ as $n \rightarrow \infty$
- if there exists two a sequence $v_n \rightarrow \infty$, a function, $m: \mathbb{R}^- \rightarrow \mathbb{R}^d$ and a $d \times d$ matrix Σ such that

$$v_n(\omega_n^{-1}(T_n - \chi_n \mathbb{I}) - f(\rho)) \xrightarrow{d} \mathcal{N}_d(m(\rho), \Sigma).$$

then

$$v_n(\hat{\rho}_n - \rho) \xrightarrow{d} \mathcal{N} \left(\frac{m_\psi(\rho)}{\varphi'(\rho)}, \frac{\sigma_\psi^2(\rho)}{(\varphi'(\rho))^2} \right) \text{ with,}$$

- ◇ $\varphi'(\rho) = {}^t f'(\rho) \nabla \psi(f(\rho))$
- ◇ $m_\psi(\rho) = {}^t m(\rho) \nabla \psi(f(\rho))$
- ◇ $\sigma_\psi^2(\rho) = {}^t \nabla \psi(f(\rho)) \Sigma \nabla \psi(f(\rho))$.

Link with existing estimators

Existing estimators

In the literature, at least two ways of estimating the second order parameter can be found :

- Estimators based on **rescaled log-spacings**, $j(\log X_{n-j+1} - \log X_{n-j})$:
 - ⇒ **Goegebeur et al.**, (*JSPI*, 2010).
- Estimators based on **log-spacings**, $\log X_{n-j+1} - \log X_{n-k}$:
 - ⇒ **Gomes et al.**, (*Extremes*, 2002),
 - ⇒ **Fraga-Alves et al.**, (*Portugaliae Mathematica*, 2003),
 - ⇒ **Ciuperca and Mercadier**, (*Extremes*, 2010).

Link with existing estimators

1. Estimators based on rescaled log-spacings : $j(\log X_{n-j+1} - \log X_{n-j})$

$$R_k(\tau) = \frac{1}{k} \sum_{j=1}^k H_\tau \left(\frac{j}{k+1} \right) j \log \frac{X_{n-j+1,n}}{X_{n-j,n}},$$

- H_τ is a kernel function integrating to one.
- This statistic is used for instance by [Beirlant et al., \(Extremes, 1999\)](#) to estimate the extreme value index γ and by [Goegebeur et al. \(JSPI, 2010\)](#) to estimate the second order parameter ρ .
- They proved asymptotic normality of these estimators under a technical condition on the kernel, denoted by **(C1)** hereafter.

Links with existing estimators

Link with our framework

Suppose the **third order condition** and **(C1)** hold. If the sequence k satisfies

$$k \rightarrow \infty, n/k \rightarrow \infty, k^{1/2}A(n/k) \rightarrow \infty,$$

$$k^{1/2}A^2(n/k) \rightarrow \lambda_A \text{ and } k^{1/2}A(n/k)B(n/k) \rightarrow \lambda_B,$$

then the random vector

$$T_n^{(R)} := \left((R_k(\tau_i)/\gamma)^{\theta_i}, i = 1, \dots, d \right),$$

satisfies the model i.e. $\omega_n^{-1}(T_n^{(R)} - \chi_n \mathbb{I}) \xrightarrow{\mathbb{P}} f^{(R)}(\rho)$ with $\chi_n = 1$,

$$\omega_n = A(n/k)/\gamma(1 + o_{\mathbb{P}}(1)),$$

$$f^{(R)}(\rho) = \left(\theta_i \int_0^1 H_{\tau_i}(u) u^{-\rho} du, i = 1, \dots, d \right)$$

Link with existing estimators

Choice of the kernel and of the function ψ

- $d = 8$, $\psi_\delta : \mathcal{D} \mapsto \mathbb{R} \setminus \{0\}$

$$\psi_\delta(x_1, \dots, x_8) = \tilde{\psi}_\delta(x_1 - x_2, x_3 - x_4, x_5 - x_6, x_7 - x_8), \text{ where } \delta \geq 0$$

$$\mathcal{D} = \{(x_1, \dots, x_8) \in \mathbb{R}^8; x_1 \neq x_2, x_3 \neq x_4, \text{ and } (x_5 - x_6)(x_7 - x_8) > 0\}.$$

$$\tilde{\psi}_\delta : \mathbb{R}^4 \mapsto \mathbb{R} \text{ texttttis given by : } \tilde{\psi}_\delta(y_1, \dots, y_4) = \frac{y_1}{y_2} \left(\frac{y_4}{y_3} \right)^\delta.$$

- $H_\tau(u) = (\tau + 1)u^\tau$, the statistic $T_n^{(R)}$ depends on 16 parameters $\{(\theta_i, \tau_i) \in (0, \infty)^2, i = 1, \dots, 8\}$.
- Let $\tilde{\theta} = (\tilde{\theta}_1, \dots, \tilde{\theta}_4) \in (0, \infty)^4$ with $\tilde{\theta}_3 \neq \tilde{\theta}_4$ and consider
 - ◊ $\{\theta_i = \tilde{\theta}_{\lceil i/2 \rceil}, i = 1, \dots, 8\}$ with $\delta = (\tilde{\theta}_1 - \tilde{\theta}_2)/(\tilde{\theta}_3 - \tilde{\theta}_4)$ with $\lceil x \rceil = \inf\{n \in \mathbb{N} | x \leq n\}$.
 - ◊ $\tau_1 < \tau_2 \leq \tau_3 < \tau_4, \tau_5 < \tau_6 \leq \tau_7 < \tau_8$
- $T_n^{(R)}$ involves 12 free parameters. $Z_n^{(R)} = \psi_\delta(T_n^{(R)})$ and $\psi_\delta \circ f^{(R)}$.

Link with existing estimators

Our contributions

- We can thus define the following family of estimators :

$$\hat{\rho}_n^{(R)} = \varphi^{-1}(Z_n^{(R)}) \mathbb{1}\{Z_n^{(R)} \in J\}.$$

- New estimators of ρ (explicit or not), with Consistency and Asymptotic normality (consequence of ours theorems)
- Examples of explicit estimators
 - ◊ $\delta = 1$ i.e. $\tilde{\theta}_1 - \tilde{\theta}_2 = \tilde{\theta}_3 - \tilde{\theta}_4$. The rv $Z_n^{(R)}$ is denoted by $Z_{n,1}^{(R)}$.

$$\hat{\rho}_{n,1}^{(R)} = \frac{\tau_5 \omega(1, \tilde{\theta}) - \tau_1 Z_{n,1}^{(R)}}{\omega(1, \tilde{\theta}) - Z_{n,1}^{(R)}} \mathbb{1}\{Z_{n,1}^{(R)} \in \omega(1, \tilde{\theta}) \bullet (1, \tilde{\psi}_1(\tau_4, \tau_1, \tau_4, \tau_5))\}.$$

- ◊ $\delta = 0$ i.e. $\tilde{\theta}_1 = \tilde{\theta}_2$. The rv $Z_n^{(R)}$ is thus denoted by $Z_{n,2}^{(R)}$:

$$\hat{\rho}_{n,2}^{(R)} = \frac{\tau_4 \omega(0, \tilde{\theta}) - \tau_1 Z_{n,2}^{(R)}}{\omega(0, \tilde{\theta}) - Z_{n,2}^{(R)}} \mathbb{1}\{Z_{n,2}^{(R)} \in \omega(0, \tilde{\theta}) \bullet (1, \tilde{\psi}_0(\tau_4, \tau_1, \tau_4, \tau_5))\}.$$

with $\omega(\delta, \tilde{\theta}) = \tilde{\psi}_\delta(\tilde{\theta}_1(\tau_1 - \tau_2), \tilde{\theta}_2(\tau_2 - \tau_4), \tilde{\theta}_2(\tau_2 - \tau_4), \tilde{\theta}_4(\tau_6 - \tau_4))$

Link with existing estimators

2. Estimators based on log-spacings : $\log X_{n-j+1} - \log X_{n-k}$

$$S_k(\tau, \alpha) = \frac{1}{k} \sum_{j=1}^k G_{\tau, \alpha} \left(\frac{j}{k+1} \right) \left(\log \frac{X_{n-j+1, n}}{X_{n-k, n}} \right)^\alpha, \quad \alpha > 0,$$

- $G_{\tau, \alpha}$ is a positive function.
- Dekkers *et al.* (*Annals of statistics*, 1989) proposed an estimator of γ based on this statistic in the particular case where $G_{\tau, \alpha}$ is constant.
- Ciuperca and Mercadier (*Extremes*, 2010) used the general statistic to estimate the parameters γ and ρ .
- They proved the asymptotic normality under a technical condition on the function $G_{\tau, \alpha}$, denoted by **(C2)** hereafter.

Link with existing estimators

Link with our framework

Suppose the **third order condition**, **(C2)** hold. If the sequence k satisfies

$$k \rightarrow \infty, \quad n/k \rightarrow \infty, \quad k^{1/2}A(n/k) \rightarrow \infty,$$

$$k^{1/2}A^2(n/k) \rightarrow \lambda_A \text{ and } k^{1/2}A(n/k)B(n/k) \rightarrow \lambda_B,$$

then the random vector

$$T_n^{(S)} = \left(\left(\frac{S_k(\tau_i, \alpha_i)}{\gamma^{\alpha_i}} \right)^{\theta_i}, i = 1, \dots, d \right)$$

satisfies the model i.e. $\omega_n^{-1}(T_n^{(S)} - \chi_n \mathbb{I}) \xrightarrow{\mathbb{P}} f^{(S)}(\rho)$ with $\chi_n = 1$,

$\omega_n = A(n/k)/\gamma(1 + o_{\mathbb{P}}(1))$, and

$$f^{(S)}(\rho) = \left(-\theta_i \alpha_i \int_0^1 G_{\tau_i, \alpha_i}(u) (\log(1/u))^{\alpha_i - 1} K_{-\rho}(u) du; i = 1, \dots, d \right),$$

Link with existing estimators

Choice of the weighted function and of the function ψ

- $d = 8$, the weighted function $G_{\tau, \alpha}$ is given by :

$$G_{\tau, \alpha}(u) = \frac{g_{\tau}(u)}{\int_0^1 g_{\tau}(x)(-\log x)^{\alpha} dx}, \quad \tau \geq 0, \alpha > 0$$

where $g_0(x) = 1$ and $g_{\tau}(x) = (\tau + 1)(1 - x^{\tau})/\tau$ if $\tau > 0$.

- 24 free parameters : $\{(\theta_i, \tau_i, \alpha_i) \in (0, \infty)^3, i = 1, \dots, 8\}$

- Let $(\zeta_1, \dots, \zeta_4) \in (0, \infty)^4$ with $\zeta_3 \neq \zeta_4$, such that

$$\{\theta_i \alpha_i = \zeta_{\lceil i/2 \rceil}, i = 1, \dots, 8\} \text{ with } \delta = (\zeta_1 - \zeta_2)/(\zeta_3 - \zeta_4).$$

$$\lceil x \rceil = \inf\{n \in \mathbb{N} | x \leq n\}.$$

- $(\tau_{2i-1}, \alpha_{2i-1}) \neq (\tau_{2i}, \alpha_{2i})$, for $i = 1, \dots, 4$ and,

$$\text{for } i = 3, 4, (\tau_{2i-1}, \alpha_{2i-1}) \leq (\tau_{2i}, \alpha_{2i})$$

Link with existing estimators

Our contributions

- We can thus define the following family of estimators :

$$\hat{\rho}_n^{(S)} = \varphi^{-1}(Z_n^{(S)}) \mathbb{1}\{Z_n^{(S)} \in J\}.$$

- New estimators of ρ (not necessarily explicit) with Consistency and Asymptotic normality.

- Exemples of explicit estimators

♦ $\delta = 0$ (i.e. $\zeta_1 = \zeta_2$), $\alpha_1 = \alpha_2 = \alpha_3 = \alpha_4 = 1$, $\tau_1 = \alpha_5 = \alpha_8 = 2$

$\tau_4 = \alpha_6 = 3$. Denoting by $Z_{n,4}^{(S)}$ the rv $Z_n^{(S)}$, the estimator of ρ is given by :

$$\hat{\rho}_{n,4}^{(S)} = \frac{6(Z_{n,4}^{(S)} + 2)}{3Z_{n,4}^{(S)} + 4} \mathbb{1}\{Z_{n,4}^{(S)} \in (-2, -4/3)\}.$$

Consider ω^* , a function depends only on δ and ζ

Link with existing estimators

Exemples of explicit estimators

◇ $\delta = 0$, $\alpha_1 = \alpha_3 = \alpha_4 = 1$, $\tau_1 = \tau_4 = \alpha_2 = \alpha_5 = \alpha_8 = 2$ and $\alpha_6 = 3$.

Denoting by $Z_{n,5}^{(S)}$ the rv $Z_n^{(S)}$,

$$\hat{\rho}_{n,5}^{(S)} = \frac{2(Z_{n,5}^{(S)} - 2)}{2Z_{n,5}^{(S)} - 1} \mathbb{1}\{Z_{n,5}^{(S)} \in (1/2, 2)\}.$$

$\hat{\rho}_{n,4}^{(S)}$ and $\hat{\rho}_{n,5}^{(S)}$ are estimators Ciuperca and Mercadier, (*Extremes, 2010*).

◇ $\delta = 1$, $\alpha_1 = \alpha_3 = \alpha_4 = 1$, $\tau_1 = \tau_4 = \alpha_2 = \alpha_5 = \alpha_8 = 2$ and $\alpha_6 = 3$

$Z_{n,6}^{(S)}$ the rv $Z_n^{(S)}$, a new estimator of ρ is given by ρ is given by

$$\hat{\rho}_{n,6}^{(S)} = \frac{3Z_{n,6}^{(S)} - 4\omega^*(1, \zeta)}{Z_{n,8}^{(S)} - \omega^*(1, \zeta)} \mathbb{1}\{Z_{n,6}^{(S)} \in \omega^*(1, \zeta) \bullet (1/2, 2/3)\}.$$

◇ $\delta = 1$ (i.e. $\zeta_1 - \zeta_2 = \zeta_3 - \zeta_4$), $\alpha_1 = \alpha_2 = \alpha_3 = \alpha_4 = 1$, denoting by $Z_{n,7}^{(S)}$ the rv $Z_n^{(S)}$, a nother new estimator of ρ is given by :

$$\hat{\rho}_{n,7}^{(S)} = \frac{Z_{n,7}^{(S)} + 4/3\omega^*(1, \zeta)}{2Z_{n,7}^{(S)} + 4/3\omega^*(1, \zeta)} \mathbb{1}\{Z_{n,7}^{(S)} \in \omega^*(1, \zeta) \bullet (-4/3, -2/3)\}.$$

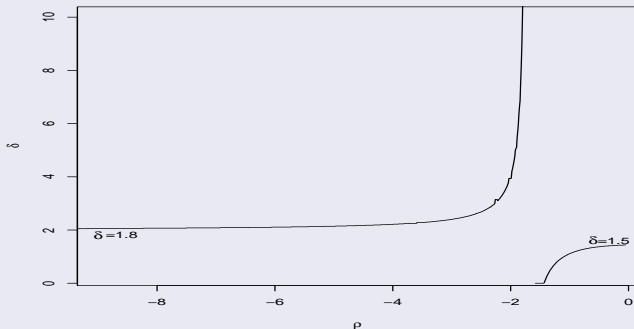
Asymptotic comparasion

Choice of the parameters

- The estimator based on rescaled log-spacings.
- $H_{\tau_i}(u) = (\tau_i + 1)u^{\tau_i}$, $i = 1, \dots, 8$.
- τ_1, \dots, τ_8 and $\tilde{\theta}_1, \tilde{\theta}_3, \tilde{\theta}_4$, taken as in Goegebeur *et al.*.
- $\tilde{\theta}_2 = \tilde{\theta}_1 + \delta(\tilde{\theta}_4 - \tilde{\theta}_3)$, $\delta \geq 0$.
- Choice of δ ,
 - ① minimization of the $AMSE$ is impossible (depends on unknown parameters).
 - ② We use an upper bound on the $AMSE$:

$$AMSE \leq c(\gamma, \lambda_A, \lambda_B)\pi(\delta, \rho, \beta).$$
 - ③ $\rho = \beta$, we minimize the function π in delta and the optimal δ as a function of ρ .

Asymptotic comparasion

Choice of δ FIG.: Optimal δ as a function of ρ

- $\delta = 0, 1, 1.5, 1.8, +\infty$

Illustration on a Burr distribution

- Burr distribution, $\text{Burr}(\zeta, \lambda, \eta) : 1 - F(x) = (\zeta / (\zeta + x^\eta))^\lambda$,
 $x > 0$, $\zeta, \lambda, \eta > 0$, $\gamma = 1/\lambda\eta$ and $\rho = -1/\lambda$.
- The third order condition is hold with $\beta = \rho$,
 $A(x) = \gamma x^\rho / (1 - x^\rho)$ and $B(x) = \rho x^\rho / (1 - x^\rho)$.
- $n = 5000$, $\gamma = \zeta = 1$, $\eta = 1/\lambda$, $\rho = -\eta$ and $k = 1, \dots, 4995$,

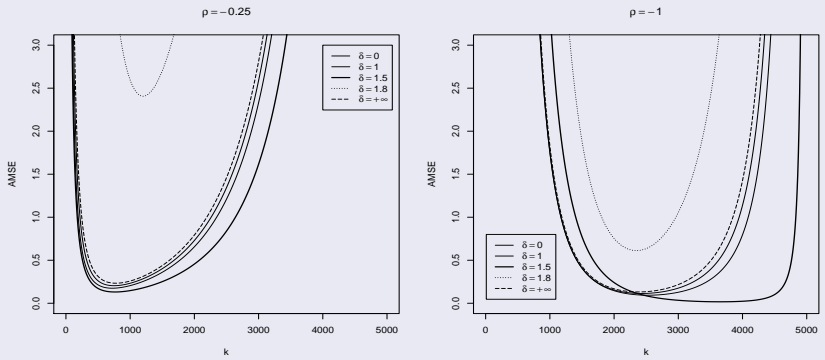


FIG.: Asymptotic mean squared error of $\hat{\rho}_n^{(R)}$, $\rho = -0.25; -1$

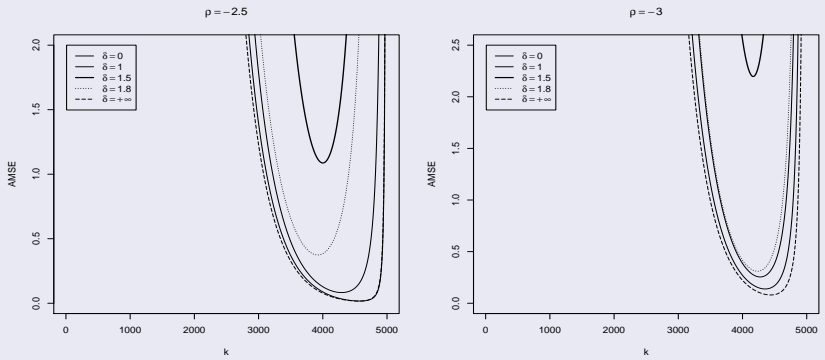


FIG.: Asymptotic mean squared error of $\hat{\rho}_n^{(R)}$, $\rho = -2.5; -3$

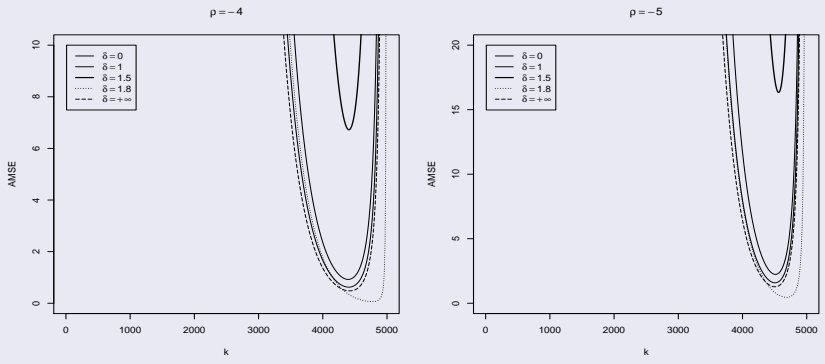


FIG.: Asymptotic mean squared error of $\hat{\rho}_n^{(R)}$, $\rho = -4; -5$

Concluding Remarks

- If $\rho \leq -4$, the smallest \mathcal{AMSE} is obtained with $\delta = 1.8$.
 - If $-3 \leq \rho \leq -2.5$, the best \mathcal{AMSE} is given by $\delta = +\infty$.
 - If $\rho \geq -1$, the smallest \mathcal{AMSE} is given by $\delta = 1.5$.
- ◇ The values $\{1.5, 1.8, +\infty\}$ obtained by minimizing the function π are also of interest to minimize the asymptotic mean-squared error.
- ◇ More generally, the minimization of π should permit to determine optimal values for the parameters of any estimator of ρ .

AND THAT'S ALL . . .