

High Dimensional Kullback-Leibler divergence for grassland classification using satellite image time series with high spatial resolution

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Outline

Introduction

High Dimensional Kullback-Leibler Divergence

Experimental results

Conclusion

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Objectives of the study

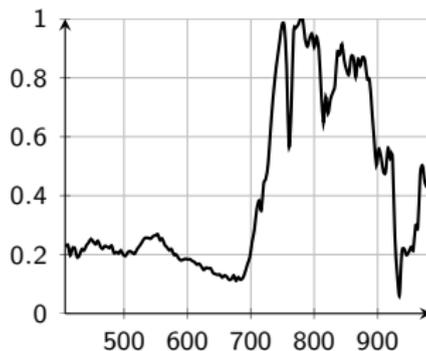
1. Characterization of grasslands through **satellite image time series (SITS)**
2. Classification of grassland **management practices**



3. Development of a **statistical modelling** of the grasslands signal suitable to SITS

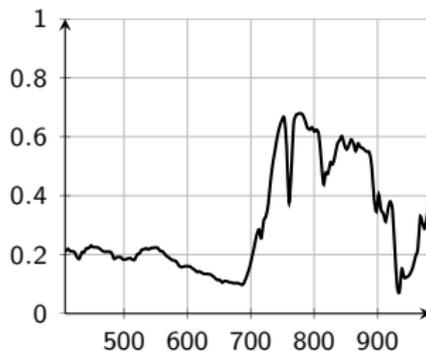
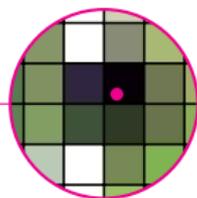
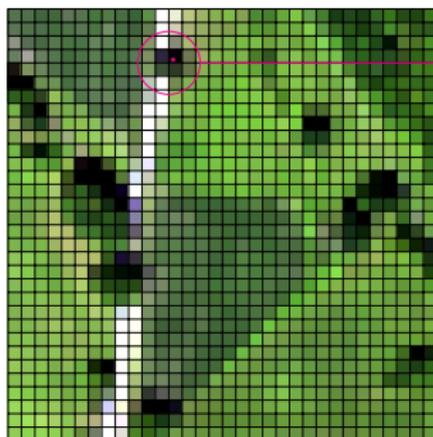
Remote sensing imagery

A digital remote sensing image corresponds to a spatial, spectral and temporal sampling of a landscape.



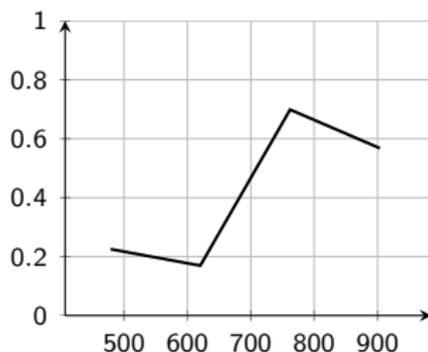
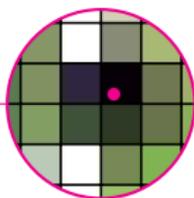
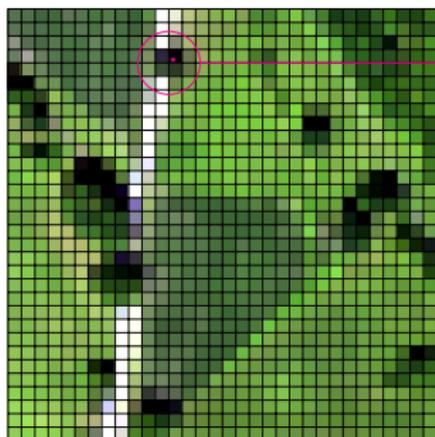
Remote sensing imagery

A digital remote sensing image corresponds to a **spatial**, spectral and temporal sampling of a landscape.



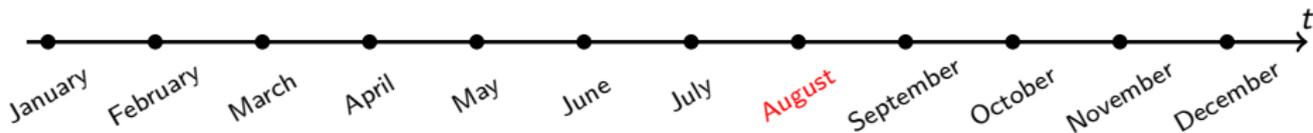
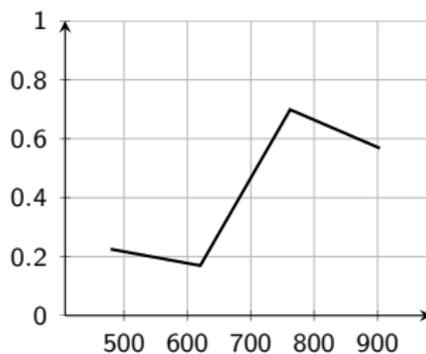
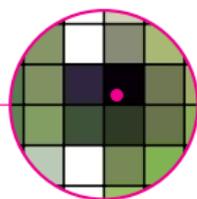
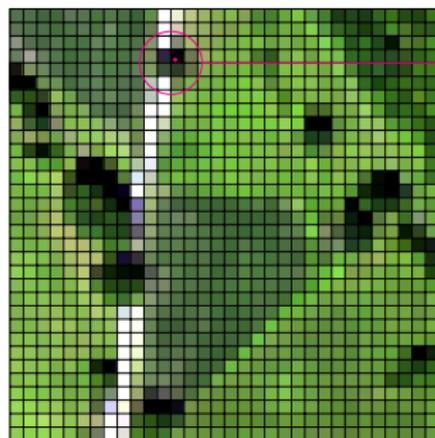
Remote sensing imagery

A digital remote sensing image corresponds to a **spatial**, **spectral** and temporal sampling of a landscape.



Remote sensing imagery

A digital remote sensing image corresponds to a **spatial**, **spectral** and **temporal** sampling of a landscape.



Satellite remote sensing of grasslands

Grasslands are:

- Relatively **small** ($\approx 100\text{m} \times 100\text{m}$) \Rightarrow need **high spatial resolution**
- **Heterogeneous** \Rightarrow need **spectral bands**
- Have a **natural vegetation cycle disturbed by anthropic events** (mowing & grazing) \Rightarrow need **high temporal resolution**



Mowing



Grazing

\Rightarrow Need dense **time series with high spatial resolution** to detect and to characterize grasslands.

Satellite image time series

Formosat-2



February



May



August

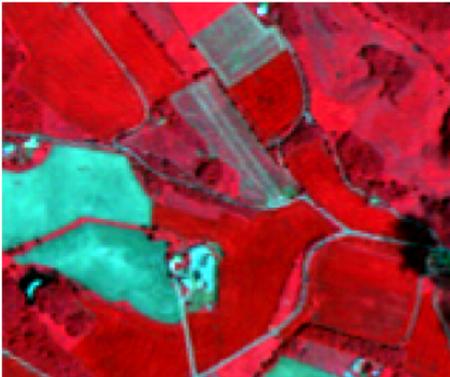


December

Normalized Difference Vegetation Index (NDVI)

NDVI: vegetation index that reflects the photosynthetic activity of the vegetation.

$$NDVI = \frac{NIR - Red}{NIR + Red}, \quad -1 \leq NDVI \leq 1$$

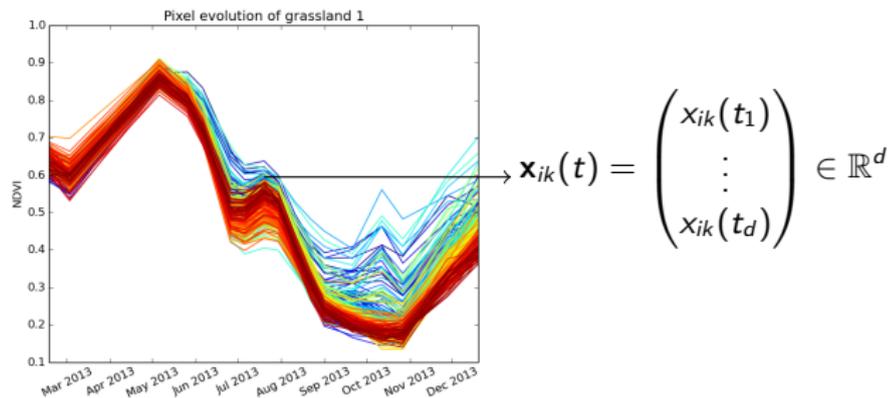


False Color (G, R, NIR)



NDVI

Representation of the grassland



with

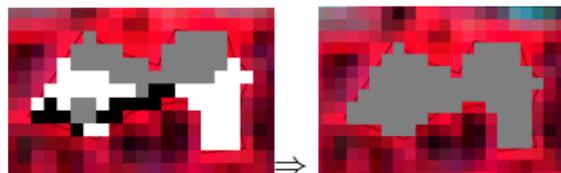
- i grassland index,
- n_i number of pixels in grassland g_i
- k pixel index, $k \in \{1, \dots, n_i\}$
- d length of time series

A grassland is represented by a matrix of size $(n_i \times d)$, n_i varying with g_i .

Statistical issues

A **statistical model** is required for:

- Processing grassland **supervised** classification
- Working at the parcel scale: **Object-oriented** classification
- **Modelling grasslands** with their constraints:
 - ▶ heterogeneity (spectral variability)
 - ▶ different size n_i
 - ▶ described by d temporal variables



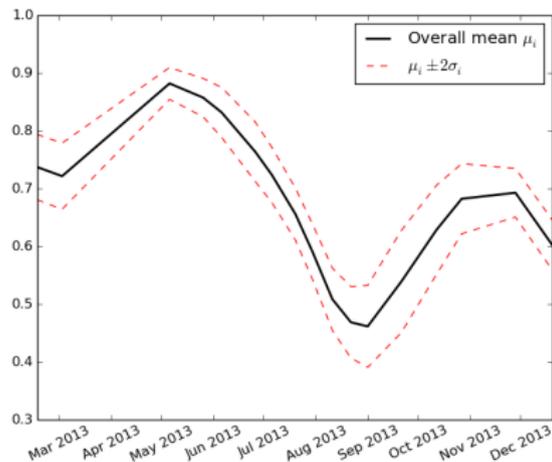
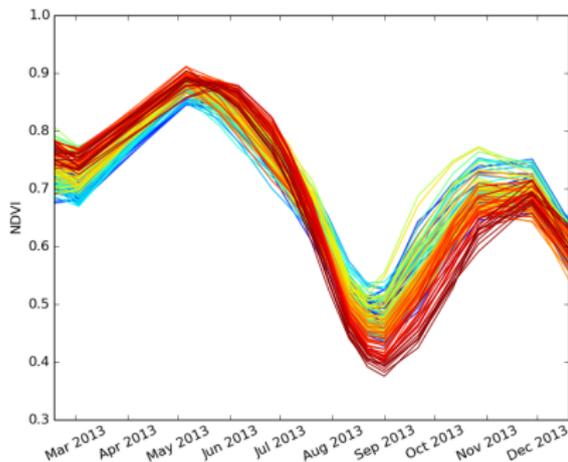
Introduction

High Dimensional Kullback-Leibler Divergence

Experimental results

Conclusion

Statistical modelling of grasslands



In each grassland g_i : each pixel $\mathbf{x}_{ik} \sim \mathcal{N}(\mu_i, \Sigma_i)$

Measuring proximity between two grasslands

Symmetrized Kullback-Leibler divergence:

$$KLD(g_i, g_j) = \frac{1}{2} \left[\text{Tr} \left[\Sigma_i^{-1} \Sigma_j + \Sigma_j^{-1} \Sigma_i \right] + (\mu_i - \mu_j)^\top (\Sigma_i^{-1} + \Sigma_j^{-1}) (\mu_i - \mu_j) \right] - d$$

- Σ_i is the covariance matrix,
- μ_i is the mean vector of the signal,
- d is the number of variables,
- Tr is the trace operator.

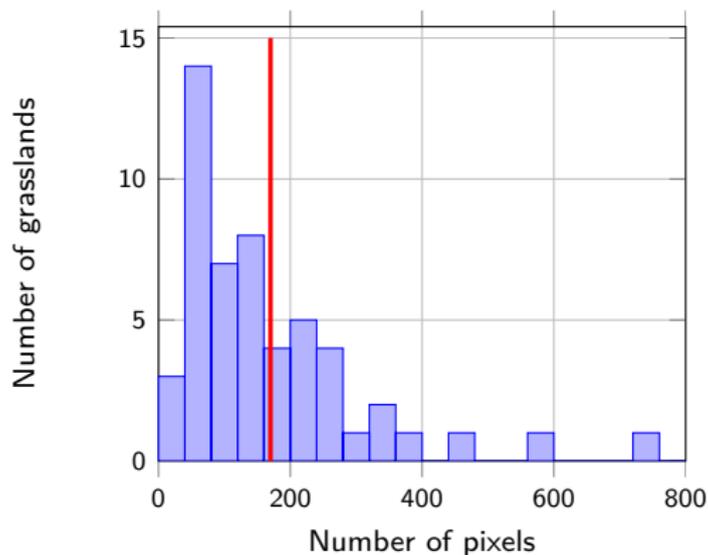


Figure : Histogram of grassland size in number of pixels n_i . The red line corresponds to the number of parameters to estimate for each grassland for a multivariate Gaussian model. It is derived from the number of variables using the formula $d(d + 3)/2 = 170$ for $d = 17$.

High dimensional model

According to High Dimensional Discriminant Analysis¹ that assumes that the last eigenvalues of the covariance matrix are equal :

$$\Lambda_i = \left(\begin{array}{ccc|ccc} \lambda_{i1} & & 0 & & & \\ & \ddots & & & & \\ 0 & & \lambda_{ip_i} & & & \\ \hline & & & \lambda_i & & 0 \\ & & & & \ddots & \\ 0 & & & & & \lambda_i \end{array} \right) \left. \begin{array}{l} \} \\ \} \end{array} \right\} \begin{array}{l} p_i \\ (d - p_i) \end{array}$$

where $\lambda_{ij} \geq \lambda_i$, for $j = 1, \dots, p_i$

¹C. Bouveyron, S. Girard and C. Schmid, "High-dimensional discriminant analysis", Communications in Statistics - Theory and Methods, vol. 36, no. 14, pp. 2607–2623, 2007

High dimensional model

According to High Dimensional Discriminant Analysis¹ that assumes that the last eigenvalues of the covariance matrix are equal :

$$\Sigma_i = \mathbf{Q}_i \mathbf{\Lambda}_i \mathbf{Q}_i^T + \lambda_i \mathbf{I}_d$$

- \mathbf{I}_d is the identity matrix of size d ,
- p_i is the number of non-equal eigenvalues,
- λ_i is the multiple eigenvalue corresponding to the noise term (last and equal eigenvalues),
- $\mathbf{Q}_i = [\mathbf{q}_{i1}, \dots, \mathbf{q}_{ip_i}]$,
- $\mathbf{\Lambda}_i = \text{diag}[\lambda_{i1} - \lambda_i, \dots, \lambda_{ip_i} - \lambda_i]$, \mathbf{q}_{ij} , λ_{ij} are the j^{th} eigenvalues/eigenvectors of the covariance matrix Σ_i , $j \in \{1, \dots, d\}$ such as $\lambda_{i1} \geq \dots \geq \lambda_{id}$.

¹C. Bouveyron, S. Girard and C. Schmid, "High-dimensional discriminant analysis", Communications in Statistics - Theory and Methods, vol. 36, no. 14, pp. 2607–2623, 2007

High Dimensional Symmetrized KLD

Following this model, Σ_i^{-1} can be computed explicitly:

$$\Sigma_i^{-1} = -\mathbf{Q}_i \mathbf{V}_i \mathbf{Q}_i^\top + \lambda_i^{-1} \mathbf{I}_d$$

with $\mathbf{V}_i = \text{diag} \left[\frac{1}{\lambda_i} - \frac{1}{\lambda_{i1}}, \dots, \frac{1}{\lambda_i} - \frac{1}{\lambda_{ip_i}} \right]$

Then:

$$\begin{aligned} HDKLD(g_i, g_j) = & \frac{1}{2} \left[-\|\Lambda_j^{\frac{1}{2}} \mathbf{Q}_j^\top \mathbf{Q}_i \mathbf{V}_i^{\frac{1}{2}}\|_F^2 - \|\Lambda_i^{\frac{1}{2}} \mathbf{Q}_i^\top \mathbf{Q}_j \mathbf{V}_j^{\frac{1}{2}}\|_F^2 \right. \\ & + \lambda_i^{-1} \text{Tr} [\Lambda_j] - \lambda_j \text{Tr} [\mathbf{V}_i] + \lambda_j^{-1} \text{Tr} [\Lambda_i] - \lambda_i \text{Tr} [\mathbf{V}_j] \\ & - \|\mathbf{V}_i^{\frac{1}{2}} \mathbf{Q}_i^\top (\boldsymbol{\mu}_i - \boldsymbol{\mu}_j)\|^2 - \|\mathbf{V}_j^{\frac{1}{2}} \mathbf{Q}_j^\top (\boldsymbol{\mu}_i - \boldsymbol{\mu}_j)\|^2 \\ & \left. + \frac{\lambda_i + \lambda_j}{\lambda_i \lambda_j} \|(\boldsymbol{\mu}_i - \boldsymbol{\mu}_j)\|^2 + \frac{\lambda_i^2 + \lambda_j^2}{\lambda_i \lambda_j} d \right] - d \end{aligned}$$

where $\|L\|_F^2 = \text{Tr}(L^\top L)$ is the Frobenius norm.

Estimation

- $\hat{\lambda}_{ij}$ and $\hat{\mathbf{q}}_{ij}$ are the first eigenvalues/eigenvectors of $\hat{\Sigma}_i$, $j \in \{1, \dots, p_i\}$,
- \hat{p}_i corresponds to the number of eigenvalues needed to reach a given percentage of variance t , $\frac{\sum_{j=1}^{\hat{p}_i} \hat{\lambda}_{ij}}{\text{Tr}(\hat{\Sigma}_i)} \geq t$, t being a user defined parameter,
- $\hat{\lambda}_i = \frac{\text{Tr}(\hat{\Sigma}_i) - \sum_{j \leq \hat{p}_i} \hat{\lambda}_{ij}}{d - \hat{p}_i}$.

Thus, to compute HDKLD only the p_i first eigenvalues/eigenvectors are required and the unstable estimation of the eigenvectors associated to small eigenvalues is avoided.

Construction of a positive definite kernel

- (HD)KLD is a semi-metric.
- It can be turned to a positive definite kernel function.
- $K(g_i, g_j) = \exp \left[- \frac{(HD)KLD(g_i, g_j)^2}{\sigma} \right]$ with $\sigma \in \mathbb{R}_*^+$

Introduction

High Dimensional Kullback-Leibler Divergence

Experimental results

Conclusion

Data

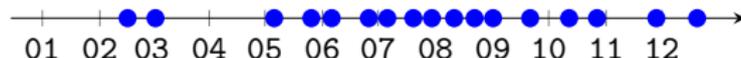
Study site Semi-rural area near Toulouse, France.

Field data 52 parcels with 3 management practices (field survey, 2015):

Class	Nb of grasslands
Mowing	34
Grazing	10
Mixed (mowing & grazing)	8
Total number of pixels:	
	8741

Satellite data **Formosat-2**

- Spatial resolution: 8m
- 4 spectral bands (B, G, R, NIR)
- Temporal frequency: up to 1 day
- $d = 17$ images from Feb. 16 to Dec. 20, 2013:



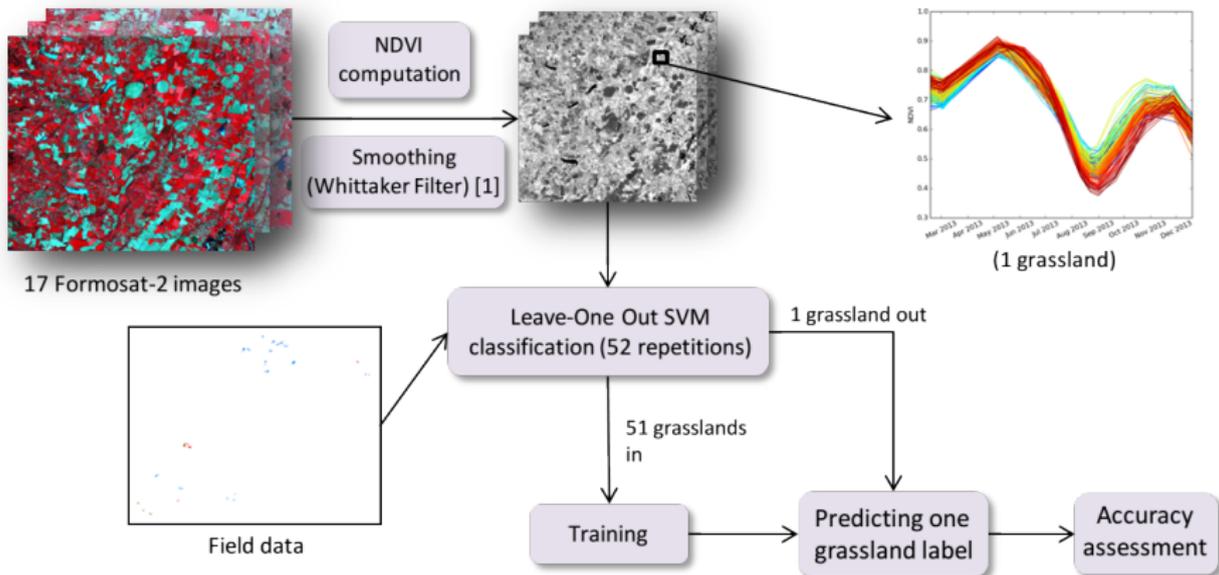
Classification methods

Method	p-SVM	μ -SVM	KLD-SVM	HDKLD-SVM
Scale	Pixel	Object	Object	Object
Expl. variable	\mathbf{x}_{ik}	μ_i	$\mathcal{N}(\mu_i, \Sigma_i)$	$\mathcal{N}(\mu_i, \Sigma_i)$
Kernel	RBF	RBF	$K(g_i, g_j)$	$K(g_i, g_j)$
Nb of samples	8741	52	52	52

+ majority rule

Optimal parameters have been optimized during cross-validation.

Processing chain



Results

Classification accuracy

	P-SVM	μ -SVM	KLD-SVM	HDKLD-SVM																																				
	REF	REF	REF	REF																																				
PRED	<table border="1"><tr><td>32</td><td>4</td><td>2</td></tr><tr><td>1</td><td>4</td><td>1</td></tr><tr><td>1</td><td>0</td><td>7</td></tr></table>	32	4	2	1	4	1	1	0	7	<table border="1"><tr><td>31</td><td>6</td><td>3</td></tr><tr><td>1</td><td>0</td><td>0</td></tr><tr><td>2</td><td>2</td><td>7</td></tr></table>	31	6	3	1	0	0	2	2	7	<table border="1"><tr><td>32</td><td>8</td><td>8</td></tr><tr><td>1</td><td>0</td><td>0</td></tr><tr><td>1</td><td>0</td><td>2</td></tr></table>	32	8	8	1	0	0	1	0	2	<table border="1"><tr><td>33</td><td>4</td><td>4</td></tr><tr><td>0</td><td>3</td><td>0</td></tr><tr><td>1</td><td>1</td><td>6</td></tr></table>	33	4	4	0	3	0	1	1	6
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OA	0.83	0.73	0.66	0.81																																				
Kappa	0.64	0.41	0.09	0.57																																				

Test of significance of observed differences

Z	p-SVM	μ -SVM	KLD-SVM	HDKLD-SVM
p-SVM	/	1.47	3.67	0.43
μ -SVM	1.47	/	2.04	1.01
KLD-SVM	3.67	2.04	/	3.11
HDKLD-SVM	0.43	1.01	3.11	/

$$Z = \frac{|\hat{K}_m - \hat{K}_n|}{\sqrt{\hat{\text{var}}(\hat{K}_m) + \hat{\text{var}}(\hat{K}_n)}}$$

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Conclusion

Conclusion and perspectives

Conclusion

- **Gaussian modelling** seems to be efficient to model grassland pixels ditribution.
- The proposed **HDKLD is efficient** for grassland classification.
- Results are not **significantly different**.

Perspectives

- The method will be tested on a **larger dataset**.
- The method will be further extended to **multispectral data**.
- The method will be used for **unsupervised classification**.

Thank you for your attention.



Questions?

Optimal parameters have been optimized during cross-validation given this search grid:

Parameter	p-SVM	μ -SVM	KLD-SVM	HDKLD-SVM
σ	$\{2^{-5}, 2^{-4}, \dots, 2^5\}$		$\{2^8, 2^9, \dots, 2^{12}\}$	
C	{1, 10, 100}			
t			{0.80, 0.85, 0.90, 0.95, 0.99}	